# Size, Select and Configure Kinetix® and PowerFlex® Drives Using Motion Analyzer Online Tool



For Classroom Use Only!





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Throughout this manual we use the following notes to make you aware of safety considerations:





Labels may be located on or inside the drive to alert people that surfaces may be dangerous temperatures.

# Size, Select and Configure Kinetix® and PowerFlex® Drives Using Motion Analyzer

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## **Before You Begin**

## **About This Lab**

Welcome to the "Size, Select and Configure Kinetix® and PowerFlex® Drives Using Motion Analyzer online tool" lab. Experience the speed and simplicity of using the new Motion Analyzer to size and select motion and drive systems. This session will premiere the new web based selection tool.

As you complete the exercises in this hands-on session, you will:

- Log in to the new Motion Analyzer website
- Follow along on a guided tour of the Motion Analyzer site
- Review a completed project
- Create a new project and select a motor and drive for a vertical lift application

This hands-on lab is ideal for:

- Individuals who size, select, and optimize motion control applications
- Mechanical engineers and controls engineers designing machines with motion control
- Machine users trying to improve an existing machine with motion control
- System integrators selling motion control

This lab takes approximately **90** minutes to complete.

#### **Tools & Prerequisites**

For this hands-on lab, the following is required to complete the exercises:

#### Software Required:

Internet Explorer Browser

#### Additional Requirements:

Valid user credentials to access the website

## Log In to the Motion Analyzer Website

Motion Analyzer has become an online tool that can be accessed from anywhere with an internet connection. By logging in, you can create new applications, access existing application data, or simply browse for drive or motor product information. Let's begin by logging into the site.

## Entering Lab User Credentials

- 1. Open Internet Explorer web browser.
- 2. Click in the web address bar and type "motionanalyzer.rockwellautomation.com" to navigate to the Motion Analyzer website.

Note: Do not type "www." prior to the web address, or the link will not take you to the correct site.

3. Enter your email address and Password by clicking on LOGIN

CREATE ACCOUNT   PLOGIN
If you do not have an account, please register using the Create Account button.
CREATE ACCOUNT   PLOGIN

## Take the Motion Analyzer Guided Tour

In this section of the Hands-On lab, you will explore the Motion Analyzer site to get accustomed to the interface.

## Understanding the Home Page

Upon logging in to the Motion Analyzer website, the home page appears. Let's take a moment to understand the key areas on this page. In the next sections we will begin to navigate through the site.



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<u>Home Button</u>: In the upper left corner of the webpage, you will find the Home button. This button is accesible from any point within the tool and will bring you back to this home page.

**Profile Management**: In the upper right corner of the webpage, you will notice your user email address and a Notifications button. This is where you modify User Profile information, manage shared library items, and access your notifications. These links are available from any point within the tool.

Navigation Tabs: On the left side of the toolbar at the top of the page, you will see several Navigation tabs labeled Products,

Library, Tools and Support. These tabs provide convenient access to the main Motion Analyzer tools from anywhere in the website.

<u>Search Tool</u>: On the right side of the toolbar at the top of the page, you will see the Search Tool. This tool can be used to search for specific product information or general support topics.

<u>Additional References</u>: Along the right side of the webpage, you will find links to additional referecences. Using these links, you can quickly view the latest Motion Analyzer news or external websites, such as the Rockwell Automation website and Literature Library. Additionally, any notifications you receive are displayed here.

**Core Sizing & Selecting Paths**: In the center of the page, you will see the two primary starting points for sizing and selecting products to meet your application requirements. The Start Building path guides you through the process of entering specific system parameters to properly size a motor and drive for your application. The Browse Product path provides access to detailed product information so that you can compare product features and options across families.

## Managing Your User Profile

Now that we have reviewed the key areas on the Motion Analyzer Home page, let's begin by taking a look at the Profile Management page.

1. Click on the **lab user email address** in the top right corner of the page.



2. Select the View Profile option.

Motion /	Analyze	1	-	L TLSTONE@RA.ROCKWELL.COM	Notifications	0 Rockwell Automation
PRODUCTS	LIBRARY	TOOLS	SUPPORT	View Profile	keyword or product #	Products 👻 🔎
			Learn.	Manage Sharing		

Find the solution for your application from Rockwell Automation and our PartnerNetwork.

## 3. The User Profile page will appear.

In the Overview tab of the User Profile page, you can change your password, update your personal information and modify the settings for units used throughout the site. For this lab, we will be entering information in metric units, which are the default settings, so there is no need to make a selection.

<b>Motion</b> A	<b>\nalyze</b>	r		TLSTONE@RA.ROCKWELL	COM V Notifications 4	Rockwell Automation
PRODUCTS	LIBRARY	TOOLS	SUPPORT		Enter keyword or product #	Products 🗙 🔎
♠ \ User Profile	2					
User Pro	ofile					
The User Profile a	llows you to upo	date your inform	ation, control yo	ur shared projects and see all no	tifications.	
Overview	Shared	Notifications	Units			
	IATION					
Username/Email	TLStone@ra.ro	ockwell.com				
Old Password						
New Password						
Repeat New Password						
U	pdate					
PERSONAL INF	ORMATION					
First Name	Tucker					
Last Name	Stone					
Company	RockwellAutom	nation				
Job Function	Engineer					
			~			
Industry		or				
	Motion and Driv	ves				
Location	North America		~			
Save Perso	onal Information					

4. Click on the **Shared** tab at the top of the User Profile page.

Motion	Analyzei	r		TLSTONE@RA.ROCKWELL.COM V Notifications 43 Rockwell Automation						
PRODUCTS	LIBRARY	TOOLS	SUPPORT		Enter keyword or product #	Products 🗸	$\mathbf{P}$			
🔒 🔪 User Profil	е									
User Pro	ofile									
The User Profile	allows you to upd	ate your informa	tion, control you	ir shared projects and see all not	ifications.					
Overview	Shared	Notifications	Units							
LOGIN INFORM	MATION									
Username/Email	TLStone@ra.ro	ckwell.com								
Old Password										

In the Shared tab of the User Profile page, you can manage your projects. Here you can share projects with other Motion Analyzer users or change the owner of a project.

5. Click on the **Notifications** tab at the top of the User Profile page.

Motion /	Analyze	er		L TLSTONE@RA.ROCKWELL.C	× MO	Notifications 43	a Roc Auton	ckwell nation
PRODUCTS	LIBRARY	TOOLS	SUPPORT		Enter key	word or product #	Products 🗸	· [ P
🛧 🔪 User Profile	9							
User Pro	ofile							
The User Profile a	allows you to up	date your informa	ation, control yo	ur shared projects and see all not	ifications.			
Overview	Shared	Notifications	Units					
LIBRARY IT	EMS OWN	ED BY ME						

In the Notifications tab of the User Profile page, you can access your notifications and change your email notification preferences.

6. Click on the **Units** tab.

Motion	Analyze	r	L TLSTONE@RA.ROC	KWELL.COM V Notifications	43 Rockwell Automation
PRODUCTS	LIBRARY	TOOLS	SUPPORT	Enter keyword or product #	Products 👻 🔎
🔒 🔪 User Pro	ofile				
User P	rofile				
The User Profil	e allows yo <mark>u to u</mark> pd	a <mark>t</mark> e your inform	ation, control your shared projects and se	ee all notifications.	
Overview	Shared	Notifications	Units		

The Units tab allows you to choose the units used in your profile.

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PRODUCTS L	IBRARY TO	DOLS SI	UPPORT		Enter keyword or product #	Products 🗸
🔒 🔪 User Profile						
User Profi	le					
The User Profile allow	/s you to update yo	our information,	, control your shared	l projects and see all not	ifications.	
Overview Sh	ared Notific	ations	Units			
SETTINGS				)		
Set Metric Units	Set Imperial Units					
	_		_			
Linear Distance	mm	Mass	kg			
Diameter	mm	Inertia	kg ⋅ cm <sup>2</sup>			
Velocity	mm/s	Force	Ν			
Acceleration	$mm/s^2$	Torque	N·m			
Jerk	mm/s <sup>3</sup>	Power	kW			
Angular Distance	rev	Time	s	<		
Angular Velocity	RPM	Temperature	٥C			
Angular Acceleration	RPM/s	Inclination	deg			
Angular Jerk	RPM/s <sup>2</sup>	Lead	mm/rev			
Density	kg/cm <sup>3</sup>	Altitude	m			
Efficiency	%					
Save Settings				J		

## Navigating Through the Website

Next, let's begin looking around the site in more detail by exploring the Navigation tabs.

## **Products Navigation Tab**

1. Click on the **Products** navigation tab on the toolbar at the top of the page.

<b>Motion</b> A	nalyzer		👤 TLS	STONE@RA.ROCKW	Notifications 4	Notifications 43 Rockw			
PRODUCTS	LIBRARY 1	rools s	UPPORT		Enter ke	yword or product #	Products	~	P
🔒 🔪 User Profile									
User Pro	file								
The User Profile a	llows you to update y	our information	, control your share	d projects and see	all notifications				
Overview	Shared Noti	fications	Units						
SETTINGS									
Set Metric Units	Set Imperial Units								
Linear Distance	mm	Mass	kg						
Diameter	mm	Inertia	kg ⋅ cm <sup>2</sup>						
Velocity	mm/s	Force	Ν						
Acceleration	mm/s <sup>2</sup>	Torque	N · m						
Jerk	mm/s <sup>3</sup>	Power	kW						

2. The Browse Products page will appear.



#### LINEAR ACTUATORS

The Browse Products page is where you go to browse and compare drives, motors, linear actuators and gearboxes.

3. Click on the Browse Drives button.



4. The Browse Drives page will appear.

<b>Motion Analy</b>	zer		TLSTONE@RA.ROCI	KWELL.COM V Notifi	cations 43 Rockwe
PRODUCTS LIBRAR	Y TOOLS	SUPPORT		product # Products V	
▲ \ Products \ Drives					
Drives					
Selection Filters clear	POCKW				Compare Selected Families (0)
Commonly Used (6)	> Drive	select	Drive select	Drive select	Drive select
Voltage & Phase (4)	>				- Distantistica
IP Ratings (4)	>				ETT
Environment (3)	>	14	.0	111 111 111 111	
Options (4)	> Kinet	ix 5500 Servo Drive	Kinetix 5700 Servo Drive	Kinetix 6000 Servo Drive	Kinetix 6200 Servo Drive
Certifications (15)	>	Sizes Available	14 Sizes Available	20 Sizes Available	10 Sizes Available
Controller (4)	> Drive	select	Drive select	Drive select	Drive select
eatures (29)	>			•	7
Motor Control (8)	>		1 a		
Network Support (14)	> Kinet	ix 6500 Servo	Kinetix 300 Servo	Kinetix 350 Servo	Kinetix 3 Servo
Bus Configuration (4)	> 10	Drive Sizes Available	Drive 12 Sizes Available	Drive 12 Sizes Available	Drive 7 Sizes Available
Safety (3)	>				
/O (14)	>		VIEW	6 MORE	
Feedback (16)	>				
Applications (1)	>				

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Here, you can select one or more drive families to see the features and options that are available for the various platforms.

5. Click **View More** to see more of the drive product families.

PRODUCTS LIBRA	ARY	TOOLS	SUPPORT			En	ter keyword or p	roduct#	Products V	Ι
A \ Products \ Drives										
Drives										
Selection Filters clear		POCKWE		MATION				Compare Se	lected Families (	(0)
Commonly Used (6)	>	Drive	select	Drive	select	Drive	select	Drive	select	
Voltage & Phase (4)	>							-	28255.5	
IP Ratings (4)	>			1.4	-		IIII	0		
Environment (3)	>	11	4	ŋ	-		1666	5		
Options (4)	>	Kinetix	5500 Servo Drive	Kinetix 57 Dri	00 Servo ve	Kinetix (	5000 Servo rive	Kinetix	6200 Servo Drive	
Certifications (15)	>	6 Siz	es Available	14 Sizes	Available	20 Size	s Available	10 Size	es Available	
Controller (4)	>	Drive	select	Drive	select	Drive	select	Drive	select	
Features (29)	>			1000		•	Commission of the local division of the loca		5	
Motor Control (8)	>	÷	<b>d</b> et			0		6		
Network Support (14)	>	Kinetix	6500 Servo	Kinetix 3	00 Servo	Kinetix	350 Servo	Kineti	x 3 Servo	
Bus Configuration (4)	>	10 Siz	<b>Drive</b> zes Available	Dri 12 Sizes	<b>Ve</b> Available	D 12 Size	rive s Available	7 Size	<b>Drive</b> Is Available	
Safety (3)	>	Drive	select	Drive	select	Drive	select	Drive	select	
I/O (14)	>	25			0		- 0		-	
Feedback (16)	>		Tra							
Applications (1)	>	(		1	111111 **** #2					
		Kinetix	7000 Servo Drive	PowerF	lex 523	Power	Flex 525	Powe	rFlex 527	
		7 Siz	es Available	33 Sizes	Available	38 Size	s Available	38 Size	es Available	
		Drive	select	Drive	select					
				and the second						
					-					
		Powe	erElex 753	PowerF	lex 755					
		205 Si	zes Aveilable	422 Sizes	Available					

6. Let's narrow the list of drive families by utilizing the product feature filters.

<b>Motion Ana</b>	lyzei	•		TLSTONE@RA.ROO	CKWELL.COM V Notif	ications 43 Rockw	vell ion
PRODUCTS LIE	BRARY	TOOLS	SUPPORT		Enter keyword o	r product # Products 🗸	$\mathbf{\rho}$
🔒 \ Products \ Drive	es						
Drives							
Selection Filters clear		ROCKWI	ELL AUTO	MATION		Compare Selected Families (0)	
Commonly Used (6)	>	Drive	select	Drive select	Drive select	Drive select	
Voltage & Phase (4)	>	-			<b></b>		
IP Ratings (4)	>	1	1	4.5			
Environment (3)	>		14	1 2	10 10 10 10		
Options (4)	>	Kinetix	c 5500 Servo Drive	Kinetix 5700 Servo Drive	Kinetix 6000 Servo Drive	Kinetix 6200 Servo Drive	
Certifications (15)	>	6 Siz	zes Available	14 Sizes Available	20 Sizes Available	10 Sizes Available	
Controller (4)	>	Drive	select	Drive select	Drive select	Drive select	
Features (29)	>				•	5	
Motor Control (8)	>	ė					
Network Support (14)	>	Kinetix	6500 Servo	Kinetix 300 Servo	Kinetix 350 Servo	Kinetix 3 Servo	
Bus Configuration (4)	>	10 Si	Drive izes Available	12 Sizes Available	12 Sizes Available	7 Sizes Available	
Safety (3)	>						
I/O (14)	>			VIEW	/ 6 MORE		
Feedback (16)	>						
Applications (1)	>	)					

7. Expand the Motor Control heading and check the Induction Volts/Hz Control check box.

Motion Analy	zer		L TLSTONE@RA.ROO	CKWELL.COM V Notif	fications 43 Rocky Automat
PRODUCTS LIBRAR	Y TOOLS	SUPPORT	1	Enter keyword o	or product # Products V
♠ \ Products \ Drives					
Drives					
Selection Filters clear	ROCKW	ELL AUTO	MATION		Compare Selected Families (0)
Commonly Used (6)	> Drive	select	Drive select	Drive select	Drive select
Voltage & Phase (4)	>		CIC IS		
IP Ratings (4)	>		C.F. E		
Environment (3)	>	14	0.1		
Options (4)	> 🚺 Kineti	x 5500 Servo Drive	Kinetix 5700 Servo Drive	PowerFlex 523	PowerFlex 525
Certifications (15)	> 85	izes Available	14 Sizes Available	33 Sizes Available	38 Sizes Available
Controller (4)	> Drive	select	Drive select	Drive select	
Features (29)	× I			-	
Motor Control (8)	$\overline{\mathbf{v}}$		-		
Interior Permanent Magnet	Bau	Annual El	BowerElex 752	PowerElax 755	
Surface Mount Permanent	38 5	Bizes Available	205 Sizes Available	422 Sizes Available	
Magnet Control		-2	VIE	NIESS	
Induction Volts/Hz Control		-	VIE	W LESS	
Synchronous Reluctance Volts/Hz Control					
Induction Sensorless Vector Control					
Synchronous Reluctance Sensorless Vector Control					
Adjustable Voltage Control (fo non-motor loads)	-				
Induction Flux Vector Control					
Network Support (14)	>				
Bus Configuration (4)	>				
Safety (3)	>				
I/O (14)	>				
Feedback (16)	>				

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The list will narrow to the Kinetix 5500, Kinetix 5700, PowerFlex 520 and PowerFlex 750 drive families.

8. Let's compare a few features for two of these drives. Check the Select boxes for the Kinetix 5500 Servo Drive and the PowerFlex 527 drive and then click on the Compare Selected Families button.



- 9. When the Compare Products page appears, select the following features in the **Add Feature** drop down menu:
  - Application Type
  - Induction Flux Vector Control
  - Surface Mount Permanent Magnet Control
  - Hardwired Safe Torque Off
  - Integrated Safe Torque Off

Motion Analyzer					KWELL COM V	Notifications 43	Auton	<mark>kwell</mark> ation
PRODUCTS	LIBRARY	TOOLS	SUPPORT		Enter	keyword or product #	Products 😽	P
♠ \ Products \	Compare							
Compare	e Produc	cts (2)						
		Kinetix 5500 S	ervo Drive	x	PowerFlex 527		1	X
Compare Family Fe	eatures					PowerfPEA H		
Add Feature Add Feature	~ _	View full inform	nation on allenbradley.com		View full informat	ion on allenbradley.com		
ATEX Analog IO Application Type	that at leas	st one product o	configuration within the	family has this fea	ature.			
Blended Moves C-Tick CE	-		Legal Notices - Pr © 2016 - Rockwell Autom	ivacy & Cookies Polic ation, Inc. All Rights F	cy Reserved.			

Motion Analyzer			Ŧ	TLSTONE@RA.RC	CKWELL CO	DM V Notifications	Aut	Rockwell omation
PRODUCTS	LIBRARY	TOOLS	SUPPORT			Enter keyword or product	# Products	* P
♠ \ Products \	Compare							
Compare	Produ	ucts (2)						
Compare Family Fe:	atures	Kinetix 5500 Servo	Drive	x	PowerFlex		x	
Application Type		Position Control, To	rque Control, Velocity Co	ontrol	Velocity Co	ntrol		x
Induction Flux Vecto Control	r	No			Yes			×
Surface Mount Perm Magnet Control	lanent	Yes			No			×
Hardwired Safe Toro Off	que	Yes*			Yes			x
Integrated Safe Toro Off	ue	Yes*			Yes			×
Add Feature	*							
More Information		View full information	n on allenbradley.com		View full inf	ormation on allenbradley.	com	

10. Here is the comparison of the selected features for the two drive families.

An asterisk (\*) indicates that at least one product configuration within the family has this feature.

#### **Encompass Partners**

1. Click on the **Products** navigation tab again.



2. Click on the Browse Gearboxes button.



3. The Gearboxes page will appear.



Here you can see there are a number of Encompass Partners and their product offerings.

## Library Navigation Tab

1. Click on the Library navigation tab on the toolbar at the top of the page.

<b>Motion Analyzer</b>	L TLSTONE@RA	ROCKWELL.COM V Notifications	Rockwell Automation
PRODUCTS LIBRARY TOOLS	SUPPORT	Enter keyword or product #	Products 👻 🔎
🔒 \ Products \ Gearboxes			

2. The Library page will appear.

Motion Analy	yzer		E@RA.ROCKWELL.COM ¥ No	tifications 0	Rockwel utomatio
	ARY TOOLS	SUPPORT	Enter keyword	or product # Product	sts 🔹 🔎
Library					
ibrary					
PROJECTS (3)			Filter by	0 Crea	te New Project
NAME	LAST MODIFIED V	DATE CREATED	OWNER	SHARED	ACTIONS
Sample Project	Sep 22, 2014	Apr 4, 2014	Rockwell Automation	Global	Action
Viewing 0 of 3	ONENTS			Create New Comp	onent 🗸
RIVE / MOTOR AXES (4)	)				
ROFILES (7)					
RANSMISSIONS (8)					
INEAR MECHANISMS (7	()				
USTOM MOTORS (0)					
RODUCT LISTS (0)					

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This is where you can access your Projects and Reusable Components. As you create application components, such as Axes, Profiles, and Transmissions, you can save them and reuse them in other Projects.

## **Tools Navigation Tab**

1. Click on the **Tools** navigation tab on the toolbar at the top of the page.



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The Tools page can be used to quickly access the Compatability Browser, Inertia Calculator, Common Bus Estimator, and Cable Selector tools. We will use the Inertia Calculator later in this lab.

## **Support Navigation Tab**

1. Click on the **Support** navigation tab on the toolbar at the top of the page.



2. The Support page will appear.

the second second second second second		LL.COM V Notifications 43 Rockwell Automation
PRODUCTS LIBRAR	Y TOOLS SUPPORT	Enter keyword or product # Products V
♠ \ Support		
SUPPORT TOPICS	Motion Analyzer Support	
All (9)		
General (8)	What are you looking for? Search Su	upport
Library (1)	TOPICS	STILL NEED HELP?
	Library Objects	Contact your local
	The Project contains all the data for a system, including projec	t components (Axes, distributor or technical
	Profiles, Transmissions, or Linear Mechanisms) customer data	a, and consultant.
	Benefits & Security of the Cloud	
	Cloud Computing is a mature & secure technology used by a	wide range of people
	in all industries for its convenience, mobility, access and scala	bility
	Additional Resources	
	Links to support documents such as labs, features explanation	ns, tutorials, etc.
	Supported Browsers	
	E97 E102 E102 E102 E102 E102 E102 E102 E102	
	Current calculation change	
	We have improved the way Motion Analyzer calculates motor	current. The impact of
	this change will vary by application but in some cases the mot	or ther
	Viewing 1 - 5 of 9 < <u>1</u> 2 >	

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The Support page is where you can go to find additional information on how to use Motion Analyzer. If you are not able to find the information you are looking for, you can find support contact information in the **Still Need Help** section of the page.

3. Click on the Library Objects topic.



4. The Library Objects page will appear.

RODUCTS	LIBRARY	TOOLS SUPPORT	Enter keyv	vord or product #	Products 🗸	P		
N Support								
SUPPORT TO All (9) General (8)	PICS	Motion Analyzer Supp What are you looking for?	Search Support					
Library (1)		LIBRARY OBJECTS						
		The Project contains all the data for a system, Linear Mechanisms) customer data, and the b in a project.	including project compone vill of materials. There are r	ents (Axes, Profile	s, Transmissio	ons, or axes		
		Project Axis Profile Transmissio	on Linear Mechanism	Custom Motor	ProductList			
		There are five sections of the project:						
		Contains basic information and a list of availal	ble actions					
		Components Detail						
		Provides detailed information on the list of components in the project. Bus Sharing between compatible drives can also be configured on this page.						
		Power Analysis Detailed power analysis and shunt and power	supply selection for the dif	řerent axes and s	hared bus sys	tems.		
		Customer/Site Project information including customer contact ambient temperature can also be configured t	t and project industry and a nere.	application. Projec	t Altitude and			
		Selected Products						
		A bill of material for all products selected in the product type. Accessories for products can also	e product. Products can be so be added. The bill of ma	viewed on an axi iterial can be expo	is by axis basi: orted to excel.	s or by		
		Projects and project components can all be sh	nared with other users. If a	project is shared	with another u	iser		

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This page has multiple tabs with information on the different types of library objects. The **Project** tab is displayed by default. The Support page will continue to be populated as the content is developed.

5. Click on Additional Resources



6. The Additional Resources page will apprear.

Motion	Analyze	r		1 TLSTONE@RA.	ROCKWELL.C	1 <b>~</b> MO:	Notifications 43	Aut	<b>ock</b> oma	well tion
PRODUCTS	LIBRARY	TOOLS	SUPPORT			Enter keyw	ord or product #	Products	*	P
🔒 \ Support										
SUPPORT TO	PICS	Motio	n Analy	zer Suppo	ort					
All (9)		14/2-04-000-04	u laskina far?		Soarch Suppo	.rt				
General (8)		vvnat are y	ou looking for?		Search Suppo					
Library (1)		ADDITIC		OURCES						
		Links to sup	port documents	such as labs, featur	es explanatior	ns, <mark>t</mark> utorials,	etc.			
		FULL INTE Introductory AXIS SIZII Creating a E Building a P Defining a L Defining a L Defining a T Selecting a I ADDITION Share Proje Changing L How to use Save Data to IMPORT D Import Data Import Data Import Data	RODUCTORY Lab - Build and NG BASICS Blank Axis and A rofile inear Mechanisu ransmission Motor and Drive VAL FEATURE Cts, Axes and C. anguage Setting Snapshots o your Compute VATA FROM I from Motion An from Motion An from Motion An from Motion An	LAB Size and Axis xis Types m S omponents with others r with an XML file IOTION ANALYZ alyzer 7.2 Method 1: alyzer 7.2 Method 3 alyzer 7.2 Method 3 alyzer 7.2 Method 4	er Users ER 7.2 OP TI Cam Profile Velocity Profi User Defined Super Review	IONS Tile J Profile W				
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The Additional Resources page is comprised of support documents such as tutorials, labs, etc. to help guide the user through different sections of Motion Analyzer.

7. When you are finished browsing, click on the **Home** button at the top of the page to return to the Home page.



## **Reviewing a Completed Project**

Now that you have become familiar with how to navigate through the website, let's take a look at the components of a completed Project.

1. In the Start Building section of the Home page, click the View Current Projects button.



2. The Library page will appear. Click on the **Sample Project**.

<b>Motion Analyze</b>	er		Notifi	cations 0 A	Rockwell utomation
PRODUCTS LIBRARY	TOOLS	SUPPORT	Enter keyword o	or product # Produ	icts 🗸 🔎
♠ \ Library					
Library					
PROJECTS (2)			Filter by .	0 Crea	te New Project
NAME	LAST MODIFIED V	DATE CREATED	OWNER	SHARED	ACTION S
Vertical Lift Application	Jan 4, 2016	Nov 17, 2014	Rockwell Automation	Global	Action
Sample Project	Sep 22, 2014	Apr 4, 2014	Rockwell Automation	Global	Action
Viewing 0 of 2	•				
REUSABLE COMPON	ENTS			Create New Compon	ent v (i)
DRIVE / MOTOR AXES (2)					>
PROFILES (2)					>
TRANSMISSIONS (2)					>
LINEAR MECHANISMS (1)					>
CUSTOM MOTORS (0)					>
PRODUCT LISTS (0)					>

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Note: This is a Global Sample project that has been shared with all of the lab user accounts for demonstration purposes. For this reason, you will not be able to modify the objects within the project. You will be creating a new project in the next section of the lab.

3. The Project Detail page will appear.

Motion Analyzer	Notifications 0 Rockwell Automation
PRODUCTS LIBRARY TOOLS SUPPORT	Enter keyword or product # Products 👻 🔎
♠ \ Library \ Sample Project	
Sample Project	E READ ONLY
This is a sample project.	TREATE A SNAPSHOT
DUPLICATE DELETE EXPORT AS XML	III RESTORE FROM SNAPSHOT
Summary Component Detail Power Analysis Customer/Site Selected Pro	ducts
Sample Project Components	AXES (2)
	PROJECT ACTIONS
> Axis: Winder Axis	Delete Create New Axis & Profile
	Create New Blank Axis
	Import Axis

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There are several tabs for viewing different aspects of your project. Let's take a moment to examine the information contained in the various tabs.

### **Component Detail Tab**

1. The Component detail tab appears as default when you open an existing project. In the center of the page you will see a list of the Project Components. This particular application contains two axes.



2. Expand the **Box Pusher Axis** by clicking the carrot next to the axis name.

Motion	Analyzeı	•			N	otifications 0	Automa	well tion
PRODUCTS	LIBRARY	TOOLS	SUPPORT		Enter keywo	ord or product #	Products 🗸	$\mathbf{P}$
🔒 \ Library \	Sample Project							
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Sample Projec	t Components					AXES (2)		
						PROJECT	ACTIONS	
> Axis: Wind	> Axis: Winder Axis				Delete	Create New Axis &		
Avis: Box					Delete	Create	New Blank Axis	
						Ir	Import Axis	

3. You can now see that the box pusher axis contains a load and motion profile, a motor and a drive but does not have a Linear Mechanism. These components can be modified by clicking on the Edit buttons.

Motion Analyzer	Notifications 0 Rockwell Automation
PRODUCTS LIBRARY TOOLS SUPPORT	Enter keyword or product # Products 🔹 🔎
▲ \ Library \ Sample Project	
Sample Project	
This is a sample project.	RESTORE FROM SNAPSHOT
DUPLICATE DELETE EXPORT AS XML	
Summary Component Detail Power Analysis Customer/Site Selected Proc	lucts
Sample Project Components	AXES (2)
> Axis: Winder Axis	Delete Create New Avis & Profile
	Oreade New Plank Avia
	Delete
Box Pusher Axis	
	View
Linear Mechanism: None Selected	
- Motor: MPL-B320P-xxxxx	
Drive: 2094-BC01-MP5-M	

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Along the right side of the page there are buttons for Project Actions. The Project Actions buttons can be used to create or import an axis or motion profile.
#### Summary Tab

1. Click on the **Summary** tab of the Project Detail page.



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In the Action Items section, you can see a list of tasks which have not yet been completed, such as selecting a shunt or power supply or create a BOM.

In the New & Changed In This Project section, you can see a list of the chages that have been made to the project as well as details about those changes.

Motion Analyze	r ·	L TLSTONE@RA.ROCKWELL.COM	➤ Notifications 0	Rockv Automat
PRODUCTS LIBRARY	TOOLS SUPPORT	En	ter keyword or product #	Products 🗸
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Summary Component Der	tail Power Analysis Custo	mer/Site Selected Products		
COMPONENTS	View All Components (2)	ACTION ITEMS	[7] Actio	ons Available
Winder Axis	•	c	Create blank Axis	
Box Pusher Axis	🚓 🖬 edit	Create an A	xis - Specify Load & Profile	
		Winder Av	kis — Set Shunt & Search	
CONTROLLER	Choose controller type	Winder Axis –	– Set Power Supply & Search	
PRODUCTS	View Selected Products	Assemble a	nd Export a Bill of Materials	
Drives 2				[E] Itoma
Cables 0		NEW & CHANGED IN T	HIS PROJECT	[5] items
Motors 2		mdlennard@ra.rockwell.com	Made Global Project Jan 12, 2015 12:45:3	8 PM
Gearboxes 2 Accessories 0			Made Private Project	
		mdlennard@ra.rockwell.com	Jan 12, 2015 11:28:5	9 AM
		mdlennard@ra.rockwell.com	Made Global Project Sep 22, 2014 4:34:46	PM
		mdlennard@ra.rockwell.com	Updated Project Sep 22, 2014 4:34:08	B PM
		mdiannard@ra raalawall.com	Updated Project	

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#### **Power Analysis Tab**

1. Click on the **Power Analysis** tab of the Project Detail page.



Legal Notices - Privacy & Cookies Policy © 2015 - Rockwell Automation, Inc. All Rights Reserved. 2. The Power Analysis tab is where you go to see the power utilization for your application. If your application requires them, you can add capacitor modules, shunts and power supplies here. Also shown is a power analysis graph.







# Customer/Site Tab

1. Click on the **Customer/Site** tab of the Project Detail page.

<b>Motion An</b>	nalyzer		上 TLS	TONE@RA.ROCKWELL.COM ✔	Notifications 0	Rockwell Automation
PRODUCTS I	LIBRARY	TOOLS	SUPPORT	Enter	keyword or product # F	Products 🖌 🔎
🔒 \ Library \ Sa	ample Project					
Sample Proje	ect				READ ONLY	
This is a sample n	project				🚔 CREATE A SNAPS	внот
	project.				RESTORE FROM	SNAPSHOT
DUPLICATE DE	ELETE EXPO	RT AS XML				
Summary Co	omponent Detail	Power Ana	alysis Customer/s	Site Selected Products		
Total Axes (2)	Shared Buses	(1) Stand	dalone Axes (0)	SELECTED SHARED	C BUS DETAIL	
CHOOSE AN ITE	EM TO VIEW					

2. The Customer/Site tab is where you update customer, industry and site information.

<b>Motion</b> A	nalyzer			L TLSTONE@RA.ROCKWE	LL.COM V Notifications	0 Rockwell Automation
PRODUCTS	LIBRARY	TOOLS	SUPPORT		Enter keyword or product #	Products 🗙 🔎
▲ \ Library \ Sample Pro This is a sample DUPLICATE	Sample Project Dject e project. DELETE EXPO	RT AS XML			A READ ONLY	<b>APSHOT</b> DM SNAPSHOT
Summary	Component Detail	Power A	nalysis Cust	omer/Site Selected Pro	oducts	
CUSTOMER IN	FORMATION			SITE		
Client	John Doe			Altitude (above sealevel)	0	m
Contact	Doe Machine	9S		Ambient Temp.	40	С
E-mail	John@Doe.c	om				
Phone	▼ 55555	55555				
USE						
Industry	Enter an Indu	istry Tag	Add			
	Packaging	x				
Application	Enter an App	lication Tag	Add			
	Flow Wrappe	er X Can	dy Bars X			

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### **Selected Products Tab**

1. Click on the **Selected Products** tab of the Project Detail page.

PRODUCTS       LIBRARY       TOOLS       SUPPORT       Enter keyword or product#       Products <ul> <li>\ Library \ Sample Project</li> <li>Sample Project</li> <li>This is a sample project.</li> <li>DUPLICATE</li> <li>DELETE</li> <li>EXPORT AS XML</li> </ul> <ul> <li>RESTORE FROM SNAPSHOT</li> <li>RESTORE FROM SNAPSHOT</li> <li>RESTORE FROM SNAPSHOT</li> <li>RESTORE FROM SNAPSHOT</li> </ul> <ul> <li>Cleant</li> <li>John Doe</li> <li>Contact</li> <li>Doe Machines</li> <li>F-mail</li> <li>John@Doe.com</li> </ul> <ul> <li>Stiffe</li> <li>Ambient Temp.</li> <li>40</li> <li>C</li> </ul> <ul> <li>Ster an Industry Tag</li> <li>Add</li> <li>Packaging</li> <li>Add</li> </ul>	ckwell nation
<ul> <li>▲ Library \ Sample Project</li> <li>▲ READ ONLY</li> <li>➡ CREATE A SNAPSHOT</li> <li>➡ CREATE A SNAPSHOT</li> <li>➡ RESTORE FROM SNAPSHOT</li> <li>■ RESTORE FROM</li></ul>	· P
Summary Component Detail Power Analysis Customer/Site   CUSTOMER INFORMATION SITE   Client John Doe   Contact Doe Machines   E-mail John@Doe.com   Phone 555555555   USE   Industry Enter an Industry Tag   Add   Packaging	r
CUS TOMER INFORMATION SITE   Client John Doe   Contact Doe Machines   E-mail John@Doe.com   Phone 5555555555   USE   Industry Enter an Industry Tag   Add   Packaging	
Client John Doe   Contact Doe Machines   E-mail John@Doe.com   Phone • 555555555   USE   Industry   Enter an Industry Tag   Add   Packaging	
Contact Doe Machines Ambient Temp. 40 C	
E-mail John@Doe.com Phone 555555555 USE Industry Enter an Industry Tag Add Packaging X	
Phone USE Industry Enter an Industry Tag Add Packaging X	
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Industry Enter an Industry Tag Add Packaging X	
Packaging X	
Application Enter an Application Tag Add	
Flow Wrapper X Candy Bars X	

Legal Notices - Privacy & Cookies Policy © 2015 - Rockwell Automation, Inc. All Rights Reserved. 2. The Selected Products tab contains product catolog numbers of the particular drives and motors you have selected in your project. You can download the project report, save these products to a Product List or Export the Bill of Materials to another program such as Microsoft Excel.

Motion Analyzer	L TLST	ONE@RA.ROCKWELL.CO	DM ♥ Notifications 43	Automatic
PRODUCTS LIBRARY TOOLS SUP	PPORT		Enter keyword or product #	Products 👻 🎉
♠ \ Library \ Sample Project				
Sample Project			🔓 READ ONLY	
This is a sample project.			🚔 CREATE A SN	APSHOT
DUPLICATE DELETE EXPORT AS XML			in RESTORE FRO	M SNAPSHOT
Summary Component Detail Power Analysis	Customer/Site	e Selected Product	s	
View by Type View by Axis	(	Download Project Report	t 🔶 Save As Product List	Export BOM
DRIVES				
CATALOG NUMBER	DESCRIPTION	QUANTITY	ACCESSORIES	ACTIONS
2094-BMP5-M / Kinetix 6500		1	1 show	View Detail
2094-BC01-MP5-M / Kinetix 6500		1	0	View Detail
MOTORS				
CATALOG NUMBER	DESCRIPTION	QUANTITY	ACCESSORIES	ACTION S
MPL-B210V-xxxxxx / MPL Motor / MPL-B210V-VJ72AA		1	2 show	View Detail
MPL-B320P-xxxxxx / MPL Motor / MPL-B320P-MJ72AA		1	2 show	View Detail

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# **Reviewing a Completed Axis**

Now that you have had the chance to review a completed project, let's take a closer look at the components of a completed axis.

1. Click on the **Component Detail** tab of the Sample Project page.

Motion Analyzer				E@RA.ROCKWELL.C	OM 🗸 N	otifications 43	Rock Automa	<b>tion</b>	
PRODUCTS	LIBRARY	TOOLS	SUPPORT			Enter keywo	rd or product #	Products 🗸	P
🔒 \ Library \	Sample Project								
Sample P	Project					6	READ ONLY		
This is a sam	ple project.					-	CREATE A SN	APSHOT	
DUPLICATE	DELETE EXP	ORT AS XML					RESTORE FR	OM SNAPSHOT	
Summary (	Component Deta	ail Power A	Analysis Cus	tomer/Site	Selected Produc	ts			

2. Click the View button for the Box Pusher Axis.

Motion /	Analyzei			L TLSTONE@R/	A.ROCKWELL.C	× N	lotifications 43	Autom	kwell ation
PRODUCTS	LIBRARY	TOOLS	SUPPORT			Enter keywo	ord or product #	Products 🗸	P
🔒 \ Library \	Sample Project								
Sample P	roject					6	READ ONLY		
This is a samp	le project.					-	CREATE A SN	APSHOT	
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Summary	Component Det	ail Power	Analysis Cu	istomer/Site S	elected Produc	ts			
Sample Project	Components						AXES (2)		
			•	_			PROJECT	ACTIONS	
> Axis: Wind	er Axis			···· - <b></b>	View	Delete	Create N	New Axis & Profile	9
> Axis: Box F	Pusher Axis		A		View	Delete	Create	New Blank Axis	
							h	mport Axis	

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3. The Components tab of the Box Pusher Axis page will appear. Let's take a look at this page in more detail.

<b>Motion Analy</b>	zer	1 TLSTONE@RA.RO	CKWELL.COM V Notificati	ons 43 Rockwell Automation
PRODUCTS LIBRAR		PORT	Enter keyword or p	roduct # Products 👻 🔎
♠ \ Library \ Sample Pro	oject \ Box Pusher Axis			
		CONTINUE TO PROJECT		
Box Pusher Axis o Linear Axis with Mecha •	Shared Users ✓ 1 Comments	×	🔒 REA 🚔 CREA 🖬 REST	D ONLY ATE A SNAPSHOT FORE FROM SNAPSHOT
Components	Performance	Dhose 3 Y	SEAD	
Voltage Tolerance V	: Voltage 400 •	Phase 5 •	SEAR	CH FOR SOLUTIONS
PROFILE			MOTOR	DRIVE
View Profile Box Pusher Profile Motion Type: Linear	Ball Screw Type: Lead Screw	Gear Reducer	MPL Motor Catalog: MPL-B320P- MJ72AA CHANGE CONFIGURATION	Kinetix 6500 Catalog: 2094-BC01-MP5-M
			ADD ACCESSORY 2090-CPBM7DF-16AA09 X 2090-CFBM7DF-CEAA09 X	

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Along the top of the components tab is the Power Requirements section. This is where you select the Voltage, Phase, and Voltage Tolerance for the application.

In the center of the page you will find the axis components. This application contains load and profile information as well as information for a ball screw linear mechanism.

4. Since a drive and motor have been selected for the application, let's take a look at the performance plots for this solution. Click on the **Performance** tab of the Box Pusher Axis page.

Motion	Analyze	r		L TLSTONE@RA.ROCKWELL.C	COM ¥ No	tifications 43	Rock Automa	well tion
PRODUCTS	LIBRARY	TOOLS	SUPPORT		Enter keyword	d or product #	Products 🗸	P
♠ \ Library \	Sample Project	\ Box Pusher	Axis					
			CON	TINUE TO PROJECT				
Box Pushe	er Axis oshare	d Users 🖌 🛛 1 C	omments 🗸		6	READ ONLY		
Ling and Asia suit	We Marsha					CREATE A SN/	APSHOT	
Linear Axis wit	th Mecha Y				2	RESTORE FRO	M SNAPSHOT	
DUPLICATE	DELETE							
Components	(	Performance						

5. The Box Pusher Axis Performance page will appear.



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The Torque/Speed Curve appears first. Here you can see where the particular segments of the motion profile fall relative to the Torque/Speed curve.

You can see the curve for additional drives or motors by clicking on the Size Up and Size Down buttons.

If a gearbox is selected for the application, you could also see how changing the gearbox impacts the Torque/Speed results.

- 6. Click on the **Power/Speed** and **Thermal** buttons to see the other Performance plots for the application.
- 7. When you are finished browsing the application performance plots, click on the **Home** button at the top of the page to return to the Home page.

Motion	Analyzer	) 🔶 🗕		TLSTONE@RA.ROCKWELL	COM V Notifications	O Roci Automa	<b>cwell</b> ation
PRODUCTS	LIBRARY	TOOLS	SUPPORT		Enter keyword or product #	Products 🗸	$\mathbf{P}$
♠ \ Library \	Sample Project	Box Pusher	Axis				
			CONT	TINUE TO PROJECT			
Box Pushe	er Axis					NADSHOT	
Linear Axis wi	th Mecha 🖌				RESTORE F	ROM SNAPSHOT	
DUPLICATE	DELETE						
Components	F	Performance					
Torque/Speed	Power/Speed	Therma	al	Summary	Drive Motor		
				Selected S	olution (2 Available)	< >	
8			+	Motor			
7				< Size Down	MPL-B320P-xxxxxx	Size Up 🗲	
				Thermal Capacity	y:	41.8%	
6				Peak Speed: Peak Torque:		36% 28.3%	
				Inertia Ratio	1.21 : 1	20.070	
(EN) e				Drive			
ondue ₹				< Size Down	2094-BC01-M01-M	Size Up 🗲	
				Thermal Capacity	y:	25.7%	
3				Average Current	-	21.5%	
				Peak Current:	<u> </u>	14%	
2	· · · ·					40.476	
1							
o							
٩	500 1,000 1,500 2, Sp	000 2,500 3,000 eed (rpm)	3,500 4,000 4,500	5,000			
_	Peak Speed	Co	ntinuous Torque		Revert	Apply	
•	Profile Operating Spe	ed • Pro	ofile Operating Toro	que			
Flip X & YAxis							

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### Size a System in Motion Analyzer



In this section of the Hands-On lab, you will model an axis in Motion Analyzer for a vertical lift and then identify an appropriate drive and motor that will meet the application requirements. You are given the following information for a new application.

Let's walk through entering this information in Motion Analyzer.

### **Creating a New Project**

1. On the home page, click the Start A New Project button.



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	DJECT	
New Blank Project	Import Project XML	
Project Name:	Vertical Lift Application	
Project Description:	This application moves a load vertically bet	petween two points
		Cancel Create Proj

3. The Customer Information section is used to enter customer specific data. You may enter some information at this point or fill it at the end section of this lab. The Ambient Temp can be entered at this point. Click the **Go to project** button.

New Blank Project	Import Project XML				
Project Name:	Vertical Lift Application				
Project Description:	This application moves a load vertical	y betweer	n two points		
	ORMATION		SITE		
Client	Rockwell Automation		Altitude (above sealevel)	0	m
Contact	Smith John		Ambient Temp.	20	<b>○</b> C
E-mail	jsmith@email.com				
Phone	• 180-040-0080				
USE					
Industry	Elevators	Add			
Application	Lift	Add			1

### **Starting Your First Axis**

1. The Project Detail page will appear. Click the Start your first Axis – Define Load & Profile button.



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**NOTE:** Both red encircled sections perform the same task in creating your profile. You may select to start your project using "Start your first Axis – Define Load & Profile" or "Create New Axis & Profile."

2. For this application, we will be selecting a rotary motor, however the load will be moving linearly. We will be utilizing a mechanism which translates the rotary motion of the motor into linear motion of the load. The motion profile is entered for the load, so in our case, we will be entering linear motion profile data.

Select Linear Axis with Mechanism from the Select Motion Type drop-down list and click the OK button.

\$	SELECT MOTION TYPE						
	Choose an option.	*					
	Choose an option.						
L	Rotary Axis						
	Linear Axis with Mechanism						
i.	Linear Axis						

3. Select Weight from the Initial Load drop-down list.

INITIAL LOAD	
Enter Name	
Select a load type 🗸 🗸	
Select a load type	
Weight	
Force	
Friction Coefficient	

4. For this application, the profile begins with the load on the vertical lift table. The table then lifts the load, stops, and the load is removed. The table then returns to the starting position and the process repeats.

Enter "Lift Load" for the name of the load. Since the profile starts with the load on the table, enter "50" kilograms as the initial point, and click the **Submit** button

	INITIAL POINT		
Uift Load	LOAD MASS	50  kg	
		SUBMIT	

### **Defining a Motion Profile**

Here is the motion profile that has been specified for the application.



Let's look at how to enter this information into the Profile page in Motion Analyzer.

1. The motion profile for this application is in terms of position. To enter a position profile data point, click anywhere on the **Position Plot**. The Add a Segment dialog box will appear.

		A	DD A SEGMENT		
	RATION		EX	САМ	
Data Depictio	n				
Specify motion p	oint values. In	itial numbers may be b	ased on click activity		
	previous point	<ul> <li>incremental</li> </ul>	<ul> <li>absolute</li> </ul>		
Time	0	976	976	ms	
Distance	0	35.337	35.337	m	
Velocity	0	72.4119	72.4119	m/s	
Average Acceleration	0	0	0	$m/s^2$	
Jerk		50		%	
				CANCEL Sub	omit

2. Change the entry units to match the image, if different, by clicking on the units button and selecting the correct unit as seen on image.

		AD	D A SEGMENT	,
	RATION		EX	САМ
Data Depiction Specify motion p	<b>n</b> oint values.	Initial numbers may be ba	ased on click activity	0
	previous point	o incremental	absolute	
Time	0	976	976	ms ms
Distance	0	35.337	35.337	m
Velocity	0	72.4119	72.4119	m/s
Average Acceleration	0	0	0	m/s <sup>2</sup>
Jerk		50		%
				CANCEL Submit

3. With the **Absolute** entry method selected, replace the pre-selected time value with "**0.5 s**" and the pre-selected velocity value with "**0 m/s**". The distance value is calculated from the velocity and time values that you enter, so you do not need to enter a value for distance.

		AD	D A SEGMENT		
	RATION		EX	САМ	
Data Depictio	n				
Specify motion p	oint values.	Initial numbers may be ba	sed on click activity		
	previous point	s O incremental	<ul> <li>absolute</li> </ul>		
Time	0	0.5	0.5	s	
Distance	0	0	0	m	
Velocity	0	0	0	m/s	
Average Acceleration	0	0	0	m/s <sup>2</sup>	
Jerk		q		%	н
					•
				CANCEL	Submit

4. Click the **Submit** button. This will produce a dwell for 0.5 seconds at the beginning of the profile.



5. Now we will add an Index segment to the plot. Click anywhere on the **Position Plot** to add a second point.



6. In the Add Point dialog box, change the segment type to Index Segment followed by Trapezoidal



**NOTE:** The Trapezoidal segment is automatically selected when entering an index segment. If you want to select a triangular segment, you will need to make the selection after clicking on Index.

With the Absolute entry method selected, replace the pre-selected time value with "2.5 s", the pre-selected Distance value with "0.75 m", and the final velocity value with "0 m/s". Next, set the Accel. and Decel. Jerk values to "0.5 %".

		ADD	A SEGMENT	
	RATION		۰ <u>۲</u>	CAM
			TRAPEZOIDAL	
Data Depiction	<b>n</b> gmnt values.	Initial numbers may be ba	sed on click activity.	
	previous point	o incremental	<ul> <li>absolute</li> </ul>	7
Time	0.5	2	2.5	s
Distance	0	0.75	0.75	m
Final Velocity	0	0	0	m/s
Jerk		acceleration	deceleration	
	[	0.5	0.5	% of time
i Absolute Velocity Limit		Specify Limit	0	m/s
				CANCEL Submit

**NOTE:** The incremental section changes as you enter your values in the absolute section. The incremental section calculates as absolute point – previous point i.e. absolute point is 2.5 s, previous point is 0.5 s, therefore incremental time is 2.5 s - 0.5 s = 2.0 s.

# 8. Click the **Submit** button.

9. Click the existin Plot to automatically zoom the Position Plot.

	Graph View	Та	ble View				Add Wind	der 📦	Add Load	🕻 Add Po	pint	Scale ∨	
					lı	nclination	0	Ğ Ti	meline Adji	ustment:	-	±	
	Seconds 👻	000	00.463	00.926	01.389	01.852	02.315 02.778	03.241	03.704	04.167	04.630	05.093	05.
🔎 Lift Load <	63.000 49.800 43.200 38.600 30.000 23.400 10.200 3.800 10.200 8.800 8.800	P											
	Seconds 🔻	000	00.463	00.926	01.389	01.852	02.315 02.778	03. <b>2</b> 41	03.704	04.167	04.630	05.093	05.
🗚 Position <	68.400 49.800 43.200 38.600 30.000 23.400 16.800 10.200 3.600 7.0000 7.0000 7.0000 7.0000 7.0000 7.0000 7.0000 7.0000 7.0000 7.0000 7.0000 7.0000 7.0000 7.0000 7.0000 7.0000 7.0000 7.0000 7.0000 7.00000 7.000000 7.00000000												
^	Velocity												
^	Acceleration												
^	Jerk		•				•						
	Seconds 👻	000	00.463	00.926	01.389	01.852	02.315 02.778	03.241	03.704	04.167	04.630	05.093	05.

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10. You can now clearly see that we have created a 0.5 second dwell segment and an index segment which moves the load to the 0.75 meter position at 2.5 seconds.

	0.788	
× 1	0.703	
E	0.023	
ž	0.040	
S	0.935	
E E	0.010	
	0.285	
	0.210	
	0.125	
Θ	m	
~		

11. Enter the remaining profile points for the application.



Note: If you need to edit any of the points that you have entered on the plot, there are three methods you can use.

<u>Click and Drag Method</u>: To adjust the value of a point on a plot, hover your mouse over the point until the icon appears. Click and drag the point to adjust the point value. Similarly, to adjust the time value of a point, hover your mouse over the time line until the icon appears. Click and drag the line to adjust the time value.

Single Click Point Method: To adjust the value of a point on the velocity plot, hover your mouse over the point until the 🕒 icon appears and click the point. The edit window will re-open. You can use this method to fine tune after using click and drag.

Table Edit Method: Alternatively, Click on the Table View button and the Table entry page will appear.

Graph Vie	w Table \	/iew		😭 Add Lo	ad 🕻 Add Point	Scale 🗸
k on the E	dit button of	f the point you	would like to e	dit.		
Motion						
ТҮРЕ	TIME (ms)	POSITION (m)	VELOCITY (m/s)	ACCELERATION (m/s^2)	JERK (m/s^3)	EDIT
Acceleration	0	0.000	0.000	0.000	0.000	Edit
Acceleration	500	0.000	0.000	0.000	0.000	Edit
Index	2,500	0.750	-0.000	-0.000	507.519	Edit
r the new	values in th	ne Edit Point d	ialog box.			

[	Graph View	Ta	ble View				I	😭 Add Winde	er 📦	Add Load	🕻 Add Po	int	Scale v	
						nclination	90		<u>Ф</u> Ті	meline Adji	ustment:	-	+	
	Seconds 🔻	000	00.556	01.111	01.667	02.222	02.778	03.333	03.889	04.444	05.000	05.556	06.111	06.0
Lift Load <	55.400 49.800 43.200 36.800 23.400 16.800 10.200 3.800													
<b>€</b>	kg				04.007		<b>b</b> a <b>77</b> 0				05 000			
D Position <	Seconds ↓ 0.765 0.823 0.540 0.458 0.375 0.293 0.210 0.128 0.045 0.243 0.243 0.245 0.243 0.245 0.243 0.240 0.458 0.375 0.293 0.210 0.128 0.210 0.210 0.223 0.540 0.755 0.223 0.540 0.755 0.293 0.210 0.0100 0.0100 0.0100 0.000 0.000 0.000 0.000 0.000 0	,	0.306	01.111	01.667	02.222	D2.778	03.383	03.889	04.444	05.000	05.356		06.1
^	Velocity Acceleration													
^	Jerk													
	Seconds 👻	D00	00.556	01.111	01.667	02.222	02.778	03.383	03.889	04.444	05.000	05.556	06.111	06.0

# 12. Since this is a vertical application, enter "90" degrees for the inclination.

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- 13. Click anywhere on the Lift Load Plot to add a point. The Add dialog opens.
  - ADD A SEGMENT TIME: 3 s LOAD MASS: 50 b CANCEL Submit
- 14. Add the "50 kilogram" load point at "3 seconds" on the Load Plot. Click the Submit button.

**NOTE:** If you were to leave the Lift Load plot without performing the above step, Motion Analyzer would assume the weight is constant at 50 kg throughout the whole profile.

15. Click on the existing icon under the Lift Load Plot. This will automatically zoom the plot.

16. When you have finished entering all of the Motion profile information, your load, position and velocity plots should look like this:



**NOTE:** If we needed to scale the entire profile, we could select **Scale** then the entire profile or horizontally and set a scale time. Our Profile plot would reflect the scale in the time x-axis.

Graph View	Table View		😪 Add Winder	Add Load	Add Point	Scale 🗸
		Inclination 90		🖒 Timeline Adju	ustment:	Entire Profile (Horizontally)

17. Click the **Save** button to save the Motion Profile for the application. Then click the **Continue to Axis** button to return to the Axis page.

Motion Analyzer				MNSECK@RA.ROCKWE	LL.COM Y No	otifications	Rock Automa	well tion
PRODUCTS	LIBRARY	TOOLS	SUPPORT		Enter keywor	d or product #	Products Y	P
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			CON					
Motion Pro	ofile /		0 Shared Users ¥	0 Comments 🗸		1 A ST	ART EDITING	
LINEAR					1		CEL CHANGE	S
DUPLICATE	DELETE IMPOR	T PROFILE	EXPORT PROFILE	CLEAR PROFILE				
Need help bu	ilding a profile? Cli	<mark>ck here for mo</mark> i	re information					
Graph View	Table View			🜍 Add Winder	😚 Add Load	🕻 Add Point	Scale 🗸	

Once you are at the axis page, you can see that it automatically saves.

Motion Analyzer			MNSECK@RA.ROCKWELL.C	сом 🗸	Notifications 0	Auton	kwell ation
PRODUCTS LIBRARY	TOOLS	SUPPORT		Enter ke	eyword or product #	Products Y	
🔒 \ Library \ Vertical Lift Applic	cation \ Axis 1						
		CONT	NUE TO PROJECT				
Axis 1 🗸 0 Shared Users 🗸	0 Comments	Ý		_	🔒 START EDITII	NG	
				- [	Automatically S	aved	
Linear Axis with Mecha V					🚔 CREATE A SN	APSHOT	
DUPLICATE DELETE					RESTORE FRO	M SNAPSHO	т

### Entering a Mechanism

Now that the load and profile information has been entered, let's begin entering the data for the mechanism. The mechanism translates the rotational motion from the motor into linear motion of the lift table.

1. Click on the **Define Custom** button for the Linear Mechanism.

Axis 1    0 Shared Users    0 Comments					
Axis 1 × 0 Shared Users V 0 Comments V Linear Axis with Mecha V DUPLICATE DELETE COMPONENTS: Voltage Select V POWER REQUIREMENTS: Voltage Select V Phase Select V SEARCH FOR SOLUTIONS ROFILE Edit Profile ofon Profile ofon Type: Linear REMOVE			CONTINUE TO PROJEC	Т	
Linear Axis with Mecha	Axis 1 🖉 🛛 Shared U	Jsers V 0 Comments V		🔒 STA	RT EDITING
Liteal Add with Media   DUPLICATE   DELETE	Lipoar Avia with Macha			💾 Autor	matically Saved
DUPLICATE DELETE	Linear Axis with Mecha			CRE.	ATE A SNAPSHOT
Components Performance   POWER REQUIREMENTS: Voltage Select V   Voltage Tolerance V   ROFILE   INEAR MECH.	DUPLICATE DELETE			ia RES	TORE FROM SNAPSHOT
Components       Performance         POWER REQUIREMENTS:       Voltage       Select         Phase Select         Select         SEARCH FOR SOLUTIONS         Voltage Tolerance         Voltage Tolerance         INFAR MECH.       MOTOR       DRIVE         Edit Profile        dion Profile        din Type: Linear        Add Partner Mechanism        Add Partner Mechanism        Add Partner Gearbox        Add Motor        Add Motor        Add Drive					
POWER REQUIREMENTS: Voltage Select Phase Select SEARCH FOR SOLUTIONS   Voltage Tolerance ~   ROFILE   LINEAR MECH.     INFAR MECH.     TRANSMISSION     MOTOR     MOTOR     DRIVE     Edit Profile   otion Profile   otion Profile   otion Type: Linear   REMOVE     Voltage     Select     Phase        Phase        Phase        Phase  Prove Description Type: Linear Remove Description Type: Linear Rem	Components	Performance			
POWER REQUIREMENTS:       Voltage       Select       Phase       Select       SEARCH FOR SOLUTIONS         Voltage Tolerance v       ROFILE       LINEAR MECH.       TRANSMISSION       MOTOR       DRIVE         Image: Constraint of the profile of ton Type: Linear REMOVE       Add Partner Mechanism       Add Partner Gearbox       Add Partner From LIBRARY       Add Partner From LIBRARY       Add Drive					
ROFILE       LINEAR MECH.       TRANSMISSION       MOTOR       DRIVE         Image: Constraint of the profile of ton Profile of ton Type: Linear REMOVE       Add Partner Mechanism       Add Partner Gearbox       Add Partner Gearbox       Add Motor       Add Motor       Add Drive         Import From Library	POWER REQUIREMENT	S: Voltage Select v	Phase Select v	SEAR	CH FOR SOLUTIONS
ROFILE       LINEAR MECH.       TRANSMISSION       MOTOR       DRIVE         Image: State of the state of t	Voltage Tolerance 🗸				
Edit Profile       Add Partner Mechanism       Add Partner Gearbox         Diffine Custom       Add Partner Gearbox       Add Motor         Define Custom       Define Custom       Add Drive         IMPORT FROM LIBRARY       IMPORT FROM LIBRARY       Add Notor					
Edit Profile       Add Partner Mechanism       Add Partner Gearbox       Add Motor       Add Drive         otion Profile       DEFINE CUSTOM       DEFINE CUSTOM       DEFINE CUSTOM       Add Drive         nmPort FROM LIBRARY       IMPORT FROM LIBRARY       IMPORT FROM LIBRARY       Add Motor       Add Motor	ROFILE	LINEAR MECH.	TRANSMISSION	MOTOR	DRIVE
Edit Profile     Add Partner Mechanism     Add Partner Gearbox     Add Motor     Add Drive       otion Profile otion Type: Linear REMOVE     DEFINE CUSTOM IMPORT FROM LIBRARY     DEFINE CUSTOM IMPORT FROM LIBRARY     Add Drive	ROFILE	LINEAR MECH.		MOTOR	DRIVE
Edit Profile     Add Partner Mechanism     Add Partner Gearbox     Add Motor     Add Drive       otion Profile otion Type: Linear REMOVE     DEFINE CUSTOM     DEFINE CUSTOM     ADD CUSTOM MOTOR	ROFILE	LINEAR MECH.	TRANSMISSION	MOTOR	DRIVE
Edit Profile     Add Partner Mechanism     Add Partner Gearbox     Add Motor     Add Drive       otion Profile otion Type: Linear REMOVE     DEFINE CUSTOM     DEFINE CUSTOM     ADD CUSTOM MOTOR	ROFILE		TRANSMISSION	MOTOR	DRIVE
Indian Profile     DEFINE CUSTOM     DEFINE CUSTOM     ADD CUSTOM MOTOR       Indian Type: Linear     IMPORT FROM LIBRARY     IMPORT FROM LIBRARY     ADD CUSTOM MOTOR	ROFILE	LINEAR MECH.		MOTOR	DRIVE
INPORT FROM LIBRARY IMPORT FROM LIBRARY	ROFILE Edit Profile	LINEAR MECH.	TRANSMISSION	MOTOR	DRIVE
REMOVE	ROFILE Edit Profile	LINEAR MECH.	TRANSMISSION	MOTOR	DRIVE
	ROFILE Edit Profile otion Profile otion Type: Linear	LINEAR MECH.	TRANSMISSION	MOTOR	DRIVE

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2. Select **Belt Drive** in the *Pick A Type* drop-down list, and click the **OK** button.



3. Enter a Name for the Belt Drive in the next dialog box, and click the **OK** button.



4. Before entering the diameter of the driver, make sure the units are in mm.

PARAMETERS					
			ER		IDLERS
	4	cm		GROUP 1	GROUI
Diameter:		mm		0	
Inertia:	kg $\cdot$ m <sup>2</sup>	in		0	
Friction Torque:	N · m	ft		0	

5. Enter "**125**" millimeters as the diameter of the Driver and Idler (Group 1) in the Parameters table.

<b>Motion</b> Ar	nalyze	r	L MNSECK@RA.	ROCKWELL.COM Y Notificatio	ns <b>Rockwell</b> Automation
PRODUCTS	LIBRARY	TOOLS SUP	PORT	Enter keyword or pro	oduct # Products V
🔒 \ Library \ Ve	rtical Lift Appli	ication \ Axis 1 \ Bel	It Mechanism		
Belt Mechan	ism / 0	) Shared Users ♥ 0 Corr	nments ¥		SAVE
BELT DRIVE F		IES			Weight of Load + Table
Load:	50 0.75	kg m		Motion - Friction Surface	Applied Force     LOAD     Diameter     of Roll
Speed:	0.5625	m/s		Driver	Belt Idler Group 1
Acceleration:	0.8459	m/s <sup>2</sup>		Motor + Transmi	issions + Gearbox
		DRIVER		IDLERS	
			GROUP 1	GROUP 2	GROUP 3
Diameter:	mm	125	125		
Inertia:	kg $\cdot$ m <sup>2</sup>	0	0		
Friction Torque:	N·m	0	0		
Number of Rollers:		1	0		
ADDITIONAL LOA Table Mass: 0	ADS	kg Belt M	Aass: 0	kg	

5. Next we will calculate the inertia of the driver which consists of two sprockets and one shaft. Click on the **Inertia Calculator** button for the Driver.

<b>Motion</b> A	nalyze	r		L MNSECK@RA.R	OCKWELL.C	OM ♥ Notifications	Automation
PRODUCTS	LIBRARY	TOOLS	SUPPORT	г		Enter keyword or produ	ct # Products v
🔒 \ Library \ Ve	ertical Lift Appl	ication \ Axis 1	\ Belt Mech	nanism			
			c	ONTINUE TO AXIS			
Belt Mechan	ism ∠ (	) Shared Users V	0 Comments	*			SAVE
DUPLICATE DE	LETE					•	
BELT DRIVE F	PROPERT	IES					
REQUIREMENT	SUMMARY	(i)					Weight of Load + Table
Load:	50	kg				Motion —>	Applied Force
Stroke:	0.75	m				Driver	TABLE of Roll
Speed:	0.5625	m/s				Ű	Belt Idler Group 1
Acceleration:	0.8459	$m/s^2$				Motor + Transmissio	ons + Gearbox
PARAMETERS							
		DRIVER	R			IDLERS	
				GROUP 1		GROUP 2	GROUP 3
Diameter:	mm	125		125			
Inertia:	kg $\cdot$ m <sup>2</sup>			0			
Friction Torque:	N · m	0		0			
Number of Rollers:		1		0			
ADDITIONAL LO	ADS						
Table Mass: 0		kg	Belt Mass:	0	kg		

6.	The Inertia Calculator tool will appear.	Select Solid Cylinder as the Type	, Steel as the Material and enter
	Sprocket 1 as Name.		

Туре:		Material:		Name:
Select A Type	• •	Select A Material	v	Element (Optional)
		SeturStandard	Enter Custom	
Density:		Mass:		Element inertia:
NaN		NaN		NaN
kg/m^3	3	kg		kg-m^2
		Save		
LOAD EL	EMENTS:			
NAME	DENSITY (KG/M^3)	MASS (KG)	INERTIA (I	KG-M^2) ACTIONS
New Total Ma	ISS:	New Total 0 kg-m^2	I Inertia	Apply Cancel

**NOTE:** Your Load Elements section might be already prefilled. Please delete the current values before entering the new calculations.

7. The length of each sprocket is **25 millimeters** and the diameter is **125 millimeters**. Enter this information into the calculator, and then click the **Save** button to add the inertia of the first sprocket to the Load Elements list.

ype:		Material:	Name:	
Solid Cylinder	~	Steel (AISI 1020)	<ul> <li>Sprocket</li> </ul>	1
		Select Standard Er	nter Custom	
		Length : 25		
				Diameter :
				125 mm
Density:		Mass:	Element iner	tia:
7900		2.424	0.005	
kg/m^3		kg	kg-m^2	
		Save		
	MENTS:			
NAME	DENSITY (KG/M^3)	MASS (KG)	INERTIA (KG-M^2)	ACTIONS
ew Total Mass:		New Total In	ertia	
0		0		Apply
kg		kg-m^2		Cancel

8. Repeat steps 6 and 7 for the second sprocket and the shaft.



9. Once you have saved all three inertia values, click the **Apply** button to enter the total inertia of the Driver into the properties table.

NAME	DENSITY (KG/M^3)	MASS (KG)	INERTIA (KG-M^2)	ACTIONS
Sprocket 1	7900	2.424	0.005	Edit   Remove
Sprocket 2	7900	2.424	0.005	Edit   Remove
Shaft	7900	5.817	0.002	Edit Remove
New Total Mass 10.664	s:	New Total Ine	rtia	Apply
kg		kg-m^2		Cancel

#### LOAD ELEMENTS:
10. For this application, there is a Single Idler group that has identical parameters to the Driver group, so we can reuse the inertia value that we calculated. **Copy** the inertia value of the Driver and **paste** it into the **Inertia field** for **Idler Group 1**.

PARAMETERS						
		DRIVER		IDLERS		
			GROUP 1	GROUP 2	GROUP 3	
Diameter:	mm	125	125			
Inertia:	kg $\cdot$ m <sup>2</sup>	0.0113	0.011285:			
Friction Torque:	N · m	0	0			
Number of Rollers:		1	0			
ADDITIONAL LOADS						
Table Mass: 0		kg Belt Mass:	0 kg			
Note: When copying, make sure to select the entire number (the entire number is not visable in the box) by						

double clicking on the number.

11. Enter **"1"** as the Number of Rollers for Idler Group 1 and enter the **Table Mass** and the **Belt Mass** under Additional Loads.



PARAMETERS

		DRIVER	IDLERS		
			GROUP 1	GROUP 2	GROUP 3
Diameter:	mm	125	125		
Inertia:	kg $\cdot$ m <sup>2</sup>	0.0113	0.0113		
Friction Torque:	N · m	0	0		
Number of Rollers:		1	1		
ADDITIONAL LOA	ads				
Table Mass: 20		kg Belt Mass:	20 kg	3	

12. Once you have entered all of the data for the Belt Mechanism, click the **Save** button and then the **Continue to Axis** button.

Motion A	Inalyzei	r	L MNSECK@RA.	ROCKWELL.COM ¥ No	tifications 0 Rockwell Automation
PRODUCTS	LIBRARY	TOOLS SUF	PPORT	Enter keyword	d or product # Products V
🔒 \ Library \ '	Vertical Lift Appli	cation \ Axis 1 \ Be	elt Mechanism		
			CONTINUE TO AXIS	2	
Belt Mecha	anism 🗸 🛛 0	Shared Users ♥ 0 Co	mments ¥		A START EDITING
DUPLICATE	DELETE				
BELT DRIVE	PROPERT	IES			
REQUIREMENT	SUMMARY	1			Weight of Load + Table
Load:	50	kg		Friction	Surface LOAD Diameter
Stroke:	0.75	m		Driver	•••••••
Speed:	0.5625	m/s			Belt Idler Group 1
Acceleration:	0.8459	$m/s^2$		Motor + T	ransmissions + Gearbox
PARAMETERS					
		DRIVER		IDLERS	
			GROUP 1	GROUP 2	GROUP 3
Diameter:	mm	125	125		
Inertia:	kg $\cdot$ m <sup>2</sup>	0.0113	0.0113		
Friction Torque:	N · m	0	0		
Number of Rollers:		1	1		
	OADS				
Table Mass: 20		kg Belt	Mass: 20	kg	

### **Entering Transmission Components**

Now we will enter the transmission data for the application.

1. Click on the **Define Custom** button for the Transmission.



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2. The first transmission we will create is the coupling. Enter a **name** for the transmission component, and click the **OK** button.

Enter a name for your new Transmission - Custom
ок 2
CANCEL

3. Select **Coupling** as the Transmission Type.

Motion	Analyze	r		MNSECK@RA.ROCKWELL.C	COM Y	Notifications 0	Auton	ckwell nation
PRODUCTS	LIBRARY	TOOLS	SUPPORT		Enter keyw	vord or product #	Products V	·
🔒 \ Library	Vertical Lift Appli	cation \ Axis 1	\ Coupling Tra	ansmission				
			со	NTINUE TO AXIS				
Coupling	Transmissior	) / 0 Shared	iUsers ♥ 0 Co	mments ¥		🔒 s1	ART EDITIN	G
						SA SA	VE	
DUPLICATE	DELETE					← CA	NCEL CHAN	GES
TRANSMIS	SION PROP	ERTIES						
Choose a transm	nission type 🛛 🗸							
Choose a transm	ission type							
Belt Drive								
Chain & Sprocke	t							
Spur Gear			Legal Notic 2016 - Rockwell	es - Privacy & Cookies Policy Automation, Inc. All Rights Reserved.				
Coupling								

4. Enter "1" for the coupling transmission ratio.

A \ Library \ Vertical Lift Application \ Axis 1 \ Coupling Transmission				
CONTINUE TO AXIS				
Coupling Transmission / 0 Shared Users v 0 Comments v	START EDITING			
	SAVE			
DUPLICATE DELETE				

#### TRANSMISSION PROPERTIES

Coupling	~			
Parameters				
Ratio:		1	i	
Inertia (motor side)		0	kg $\cdot$ m $^2$	i
Efficiency:			% i	
Friction Torque (motor side)		0	N·m (i	

Coupling must be chosen carefully to avoid backlash and provide a high degree of stiffness.

NOTE: For efficiency, your initial unit may be a dash "-" if you have not set the unit to % in the units tab of your user Profile.

5. Enter the remaining data that was provided for the coupling.



6. Once the coupling data has been entered, click on the Save button and then the Continue to Axis button.

A \ Library \ Vertical Lift Application \ Axis 1 \ Coupling Transmission					
CONTINUE TO AXIS	3				
Coupling Transmission / 0 Shared Users v 0 Comments v					
DUPLICATE DELETE	↑ CANCEL CHANGES				

#### TRANSMISSION PROPERTIES

Coupling	*			4
Parameters				
Ratio:		1	(i)	
Inertia (motor side)		0.0034	kg $\cdot$ m <sup>2</sup> i	
Efficiency:		100	% i	
Friction Torque (motor side)		0	N·m i	
				_

Coupling must be chosen carefully to avoid backlash and provide a high degree of stiffness.

7. Now we will add the second transmission component. Click on the **Add Another** button under the Transmission heading.

Components	Performance			
POWER REQUIREMEN	NTS: Voltage Select v	Phase Select v	SEAR	CH FOR SOLUTIONS
PROFILE	LINEAR MECH.	TRANSMISSION	MOTOR	DRIVE
	- <b></b> -	0,0	-	Ę
Edit Profile		Add Another	Add Motor	Add Drive
Motion Profile	Belt Mechanism	Coupling Transmission	ADD CUSTOM MOTOR	
Motion Type: Linear	Type: Belt Drive	REMOVE	<b>T</b>	
REMOVE	REMOVE		<b>\</b>	

8. Click on the **Define Custom** button under the new transmission heading you just added.

Components	Performance				
POWER REQUIREMENTS	Select Voltage	Phase Select v	SEAR	CH FOR SOLUTIONS	
PROFILE	LINEAR MECH.	TRANSMISSION	TRANSMISSION	MOTOR	DRIVE
	- <b></b> -¢	<b>\$</b> \$	<b>\$</b> \$	-	<b>!</b>
Edit Profile		Add Another	Add Partner Gearbox	Add Motor	Add Drive
Motion Profile	Belt Mechanism	Coupling Transmission	DEFINE CUSTOM	ADD CUSTOM MOTOR	
REMOVE	REMOVE	REMOVE	IMPORT FROM LIBRARY		
		< Move >	< Move >		

9. The second transmission we will create is the belt. Enter a name for the transmission component, and click the **OK** button.



10. Select **Belt Drive** as the transmission type.

♠ \ Library \ Vertical Lift App	lication \ Axis 1 \ Belt Transmission	
	CONTINUE TO AX	IS
Belt Transmission /	0 Shared Users ¥ 0 Comments ¥	🔒 START EDITING
DUPLICATE DELETE		
TRANSMISSION PROP	ERTIES	
Choose a transmission type 🗸 🗸		
Choose a transmission type Bett Drive		
Chain & Sprocket		
Spur Gear	Legal Notices - Privacy & Cook © 2016 - Rockwell Automation, Inc. All	ies Policy Rights Reserved.
Coupling		

11. Enter the data that was provided for the belt.



12. Once the belt data has been entered, click on the Save button and then click the Continue to Axis button.



13. Although a gearbox is not needed for this application, let's take a look at the steps you would follow to add one. Begin by clicking the **Add Another** button.

N·m i

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0

Components	Performance				
POWER REQUIREMENTS	S: Voltage Select v	Phase Select v	SEAF	CH FOR SOLUTIONS	
PROFILE	LINEAR MECH.	TRANSMISSION	TRANSMISSION	MOTOR	DRIVE
	¢	<b>\$</b> \$	<b>\$</b> \$	-	
Edit Profile		Add Another	Add Another	Add Motor	Add Drive
Motion Profile	Belt Mechanism	Coupling Transmission	Belt Transmission	ADD CUSTOM MOTOR	
Motion Type: Linear	Type: Belt Drive	REMOVE	REMOVE		
REMOVE	REMOVE	< Move >	< Move >		

Efficiency:

Friction Torque (motor side)

14. Click on the Add Partner Gearbox button for the Transmission that you just added.

POWER REQUIREMENT: Voltage Tolerance V	S: Voltage Select v	Phase Select v	SEAR	CH FOR SOLUTIONS		
PROFILE	LINEAR MECH.	TRANSMISSION	TRANSMISSION	TRANSMISSION	MOTOR	DRIVE
		<b>\$</b> \$	<b>\$</b> \$	<b>\$</b> \$	-	÷
Edit Profile		Add Another	Add Another	Add Partner Gearbox	Add Motor	Add Drive
Motion Profile	Belt Mechanism	Coupling Transmission	Belt Transmission	DEFINE CUSTOM	ADD CUSTOM MOTOR	
REMOVE	REMOVE	REMOVE	REMOVE	IMPORT FROM LIBRARY		
		< Move >	< Move >	< Move >		

15. From the Specify Partner Gearbox window, select a manufacturer.

:		RBO	x		x
	Select a manufacturer v	Sele	ect a method for adding your g	jearbox below	
	Stober Drives				
	Nidec-Shimpo				CANCEL
	Wittenstein Alpha	_			
dit I	Apex Dynamics		Add Another	Add Another	Add Partner Ge
ile	Harmonic Drive		Coupling Transmission	Belt Transmission	DEFINE CUS
e: L	Select a manufacturer		REMOVE	REMOVE	DEFINE COS

**NOTE:** We selected Wittenstein Alpha geabox on this lab, you can select any manufacturer to compare its available gearboxes. Here is an example of 3 products compared:

A V Products V Comp	bare			
Compare P	roducts (3)			Go to Axis
	C-Series X	KL-Series	PA-Series X	
Compare Family Features		Col	ST	
Catalog Number	C402_0310MT30*	KL202_0160MQ*	PA722_0320MF/35*	x
Configuration	In-Line	Right-Angle	In-Line	x
Manufacturer	Stober Drives	Stober Drives	Stober Drives	×
Туре	Helical	Helical	Planetary	×
More Information	View full information on allenbradley.com	View full information on allenbradley.com	View full information on allenbradley.com	

An asterisk (\*) indicates that at least one product configuration within the family has this feature.

16. You will have two option on how to select your gearbox. Let's select option 1.

SPECIFY PARTNER GEARBOX	x
Wittenstein Alpha	adding your gearbox below
Want to search for your gearbox? Select one or more families in browser below.	2 Know your gearbox? Enter it by Catalog Number.
Browse for Families, Products or Configuration	Enter Catalog Number
	Select a family ¥
	ADD TO AXIS
	CANCEL

**NOTE**: On the new update of MA online tool, the gearbox selection has been changed to allow you to add filters of either families or individual products. If you would like to add a specific gearbox directly to your axis (instead of specifying a prefilter for search), use the section on the right side of the Add Partner Gearbox model and type in the gearbox you want to use.

## 17. Your selected manufacturer's Gearboxes will be displayed

Motion A	Analyz	er		MNSECK@RA.ROO	CKWELL.COM Y Not	ifications 0 Au	Rockwell Itomation
PRODUCTS	LIBRARY	TOOLS	SUPPORT		Enter keyword	or product # Product	ts 🔺 🔎
🔒 \ Axis \ Ge	arboxes						
Gearbox	es				Add S	elected Families to Axis	Go to Axis
Selection Filters cl	ear	WITTE	NSTEIN ALP	HA		Compare Selected Fi	amilies (0)
Commonly Used	(4)	Gearb	IOX select	Gearbox select	Gearbox select	Gearbox s	elect
Physical Dimensi	ion (6)				a) 0		
Torque & Speed	Ratings (7)			<b>P</b> PP			21
		BI	EVEL RIGHT- ANGLE 8 Sizes Available	HYPOID RIGHT- ANGLE 1085 Sizes Available	PLANETARY IN- LINE 1102 Sizes Available	WORM RIGH ANGLE 110 Sizes Availab	T-
			Select	Select	Select	Select	

Legal Notices - Privacy & Cookies Policy © 2016 - Rockwell Automation, Inc. All Rights Reserved. 18. Select to compare the Bevel Right-Angle and Planetary In-Line gearboxes.



19. The Compare Products window will open up and the comparison fields will be load

♠ \ Products \ Compare			
Compare Produc	cts (2)		Go to Axis
	BEVEL RIGHT-ANGLE	PLANETARY IN-LINE	
Compare Family Features	No	I PB090S.MF2.40.1G1*	X
Configuration	Right-Angle	In-Line	x
Manufacturer	Wittenstein Alpha	Wittenstein Alpha	x
Туре	Bevel	Planetary	×
Add Feature Y Add Feature Wittenstein Series	View full information on allenbradley.com	View full information on allenbradley.com	

An asterisk (\*) indicates that at least one product configuration within the family has this feature.

**NOTE:** You can add features to your selected comparisons for more options. This "Add Feature" option is available for all product comparisons.

- Go to Axis
- 20. Assuming you prefer the Planetary In-Line gearboxes, click on the product name

This will take you to the product detail page where you can choose size and set configuration

21. Click on Choose Size.



# 22. You are able to view the different selections in two formats

# Vertical View - 4 products per page

0 Filters Applied clear		Base Product Info	Choo	se Size	Set Configu	Iration			
Commonly Used (3)	>				Ŭ				
Physical Dimension (6)	)	1102 total items (filte	ered from 1102)	123156	276				
Torque & Speed Ratings (7)	)	The total homo (inte							
		SELECT A SIZE	SELECT	SELECT	SELECT	SELECT			
		FEATURES							
		Catalog Number	CP040-MO1-10-111	CP040-MO1-4-111	CP040-MO1-5-111	CP040-MO1-7-111			
		Axial Load	230	230	230	230			
		Max Input Speed (rad/s)	8000.000563816463	8000.000563816463	8000.000563816463	8000.000563816463			
		Output Max Torque (Nm)	10.5	10.5	11.5	11.5			
		Radial Load	200	200	200	200			
		Ratio	10	4	5	7			
		Stage Number	1	1	1	1			
		Weight (kg)	0.31	0.31	0.31	0.31			

# Horizontal View - 20 products or more per page

0 Filters Applied clear	Base Produ	ct Info	Choose Size		Set Configuration	
Commonly Used (3)						
Physical Dimension (6)	1102 total it	tems (filtered from 1102)				
Torque & Speed Ratings (7)		,				
	SELECT	Catalog Number	Ratio	Output Max Torque	Max Input Speed	Stage Number
		CP040-MO1-10-111	10	10.5	8000.000563816463	1
		CP040-MO1-4-111	4	10.5	8000.000563816463	1
		CP040-MO1-5-111	5	11.5	8000.000563816463	1
		CP040-MO1-7-111	7	11.5	8000.000563816463	1
		CP040-MO2-100-111	100	10.5	8000.000563816463	2
		CP040-MO2-16-111	16	10.5	8000.000563816463	2
		CP040-MO2-20-111	20	10.5	8000.000563816463	2
		CP040-MO2-25-111	25	11.5	8000.000563816463	2
		CP040-MO2-35-111	35	11.5	8000.000563816463	2
		CP040-MO2-50-111	50	11.5	8000.000563816463	2
		CP040-MO2-70-111	70	11.5	8000.000563816463	2
		CP060-MO1-10-111	10	29	5999.999706665103	1
		CP060-MO1-4-111	4	32	5999.999706665103	1
		CP060-MO1-5-111	5	32	5999.999706665103	1
		CP060-MO1-7-111	7	32	5999.999706665103	1
		CP060-MO2-100-111	100	29	5999.999706665103	2
		CP060-MO2-16-111	16	32	5999.999706665103	2
		CP060-MO2-20-111	20	32	5999.999706665103	2
		CP060-MO2-25-111	25	32	5999.999706665103	2
		CP060-MO2-35-111	35	32	5999.999706665103	2
			VIEW	V 20 MORE		

23. We will not be adding a gearbox to this project. Please select **Go to Axis** button to return to the axis page without selecting a gearbox.



## SELECTION SUMMARY

Not Selected	
Not Selected	
Not Selected	
	Not Selected Not Selected Not Selected

Save Axis

Go to Axis

### Selecting a Motor and Drive

Now that you have entered all of the mechanical and motion profile data into Motion Analyzer, you are ready to select a Drive and Motor for the application.

1. Begin by selecting **460** for the Voltage and **3** for the Phase in the Power Requirements section of the Axis page. Your axis is now automatically saved.



2. Next, click on the Search for solutions button.

Components	Performance				
POWER REQUIREMENTS Voltage Tolerance 🗸	: Voltage 460 ¥	Phase 3 v	SEAR	CH FOR SOLUTIONS	
PROFILE	LINEAR MECH.	TRANSMISSION	TRANSMISSION	MOTOR	DRIVE
	- <b></b> -	<b>\$</b> ,*	<b>\$</b> \$\$	-	ŧ
Edit Profile		Add Another	Add Another	Add Motor	Add Drive
Motion Profile Motion Type: Linear REMOVE	Belt Mechanism Type: Belt Drive REMOVE	Coupling Transmission REMOVE < Move >	Belt Transmission REMOVE < Move >	ADD CUSTOM MOTOR	

3. After Motion Analyzer performs the necessary calculations, the Solution List will appear with a list of the motor and drive combinations which meet the application requirements.

OLUTIONS LIST	Viewing 1 - 10 of 35 < <u>1</u> 2	3 4 > Soll	Dy. PIO	lie Match (	(%)	Ť		
Clear Filters	Note: Some solutions may ha	ve accessories added	to meet y	our filter	criteria.			
Solution Filters	> Filter Solutions by Pr	oduct Family						
Solution Filters (6)	> Drive	View T	orque Spee	ed Curve			Sele	ct
Motor Filters	Motor	Profile	Relative	Average	Force Or	Inertie	Peak	Thermal
Commonly Used (6)	Stober EZM Motor   EZM702WS	O Match	Price	Current	Torque Utilization	Ratio	Current Utilization	Capacity
Torque/Force Ratings (6)	Gearbox >	80.2%	222220	7.55	55.1%	0.04	57.6%	58.7%
Induction Motor (5)	> Drive	) faur T					Solo	ot
Physical Dimension (3)	Kinetix 5500   2198-H040-ERSx	View I	orque Spee	ed Curve			Sele	
Options (14)	VPL Motor   VPL-B1306C-x00000	Profile Match	Relative Price	Average Current	Force Or Torque	Inertia Ratio	Peak Current	Thermal Capacity
IP Ratings (5)	Gearbox	79.6%	<b>\$\$</b> \$\$\$\$\$	9.43	86.3%	62.17	87.3%	79.4%
Certifications (3)	> Drive						_	
Environment (3)	Kinetix 5700   2198-D032-ERS3	View To	View Torque Speed Curve				Select	
Feedback (2)	VPL Motor   VPL-B1306C-x00000	Profile Match	Relative Price	Average Current	Force Or Torque	Inertia Ratio	Peak Current	Thermal Capacity
Group (1)	> Gearbox	79.6%	<b>\$\$\$</b> \$\$\$	9.43	Utilization 86.3%	62.17	Utilization 87.3%	79.4%
Drive Filters		•						
Commonly Used (7)	> Kinetix 6500   2094-BM02-M	View T	orque Spee	ed Curve			Sele	ct
Voltage & Phase (4)	Stober EZS Motor   EZS702US_	D Profile	Relative	Average	Force Or Torque	Inertia Ratio	Peak	Thermal
IP Ratings (5)	> Gearbox	79.3%	\$\$\$\$\$	7.80	Utilization 82.5%	19.75	Utilization 84.4%	76.7%
Environment (3)	>	•						
Options (4)	> Drive Kinetix 6500   2094-BM01-M	View T	orque Spee	ed Curve			Sele	ct
Certifications (19)	> Motor	Profile	Relative	Average	Force Or	Inertia	Peak	Thermal
Controller (4)	Gearbox	Match 79.1%	Price \$\$\$\$\$\$	Current 7.08	Torque Utilization 85.3%	Ratio 18.79	Current Utilization 78.6%	Capacity 91.8%
Features (35)	>	•						

SOLUTIONS LIST View	ving 1 - 10 of 35 < <u>1</u> 2 3 4 >	Sort t	oy: Profi	ile Match (	%)	~		
Clear Filters	Note: Some solutions may have accessori	es added	to meet y	our filter	criteria.			
Solution Filters	Filter Solutions by Product Family	<u></u>						
Solution Filters (6)	Drive Kinetix 8500   2094-BM02-M	View To	orque Spee	Select				
Motor Filters	Motor	Profile	Polativa	Average	Earso Or	Inortio	Peak	Thormal
Commonly Used (6)	Stober EZM Motor   EZM702WS_O	Match	Price	Current	Torque Utilization	Ratio	Current Utilization	Capacity
Torque/Force Ratings (6)	Gearbox	80.2%	\$\$\$\$\$\$	7.55	59.1%	8.84	57.6%	58.7%
Induction Motor (5)		ad Curve			Sele	et		
Physical Dimension (3)	Kinetix 5500   2198-H040-ERSx	View It	nque Spee	su Cuive				
Options (14)	Motor VPL Motor   VPL-B1306C-xxxxxxx	Profile Match	Relative Price	Average Current	Force Or Torque	Inertia Ratio	Peak Current	Thermal Capacity

4. Click the **Expand** button next to Product Family Matrix.

5. Here you can view a table of all the drives and motors that fit the solution.

*	By Drive Family 🗸 a	and By	/ Motor Fami	ly	~			
oduct Family			KINETIX 5500 SERVO DRIVE	KINETIX 5700 SERVO DRIVE	KINETIX 6000 SERVO DRIVE	KINETIX 6200 SERVO DRIVE	KINETIX 6500 SERVO DRIVE	KINE 700 SER' DRIV
by Pr	EZF HOLLOW-BORE MOTOR	2	0	0	0	0	4	0
ions	EZM HOLLOW-BORE MOTOR	R	0	0	0	0	4	0
Solut	EZS HOLLOW-BORE MOTOR	ł	0	0	0	0	4	0
ilter	HPK-SERIES SERVO MOTOR	\$	0	2	0	0	0	2
"	MP-SERIES LOW INERTIA SERVO	NOTOR	0	0	0	0	0	1
	RDD-SERIES DIRECT DRIVE		0	0	4	3	3	0
	SX-SERIES EXPLOSION PROOF M	IOTOR	0	0	1	1	1	0
	VP LOW INERTIA SERVO MOTO	OR	2	3	0	0	0	0
	<							>

Note: Some solutions may have accessories added to meet your filter criteria.

6. Let's narrow the search results by selecting the Kinetix 5700 Servo Drive Family. Click on the **KINETIX 5700 SERVO DRIVE** heading in the Product Family table.

Note: \$	ote: Some solutions may have accessories added to meet your filter criteria.								
*	By Drive Family	andE	By Motor Fam	ily	1				
oduct Family			KINETIX 5500 SERVO DRIVE	KINETIX 5700 SERVO DRIVE	KINETIX 6000 SERVO DRIVE	KINETIX 6200 SERVO DRIVE	KINETIX 6500 SERVO DRIVE	KINE 700 SER <sup>1</sup> DRI1	
by Pro	EZF HOLLOW-BORE MOTO	R	0	0	0	0	4	0	
ions	EZM HOLLOW-BORE MOTO	R	0	0	0	0	4	0	
Solut	EZS HOLLOW-BORE MOTO	R	0	0	0	0	4	0	
ilter	HPK-SERIES SERVO MOTOR	RS	0	2	0	0	0	2	
	MP-SERIES LOW INERTIA SERVO	MOTOR	0	0	0	0	0	1	
	RDD-SERIES DIRECT DRIVI	E	0	0	4	3	3	0	
	SX-SERIES EXPLOSION PROOF	NOTOR	0	0	1	1	1	0	
	VP LOW INERTIA SERVO MOT	OR	2	3	0	0	0	0	
	<							>	

7. Collapse the Product List by clicking on the carrot for the list.

-

Note:	Note: Some sections may have accessories added to meet your filter criteria.								
~	By Drive Family	and	By	Motor Fami	Motor Family				
oduct Family				KINETIX 5500 SERVO DRIVE	KINETIX 5700 SERVO DRIVE	KINETIX 6000 SERVO DRIVE	KINETIX 6200 SERVO DRIVE	KINETIX 6500 SERVO DRIVE	KINE 700 SER <sup>1</sup> DRI1
by Pr	EZF HOLLOW-BORE MO	TOR		0	0	0	0	4	0
ions	EZM HOLLOW-BORE MO	TOR		0	0	0	0	4	0
Solut	EZS HOLLOW-BORE MO	TOR		0	0	0	0	4	0
ilter	HPK-SERIES SERVO MOT	ORS		0	2	0	0	0	2
	MP-SERIES LOW INERTIA SERV	ю мот	OR	0	0	0	0	0	1
	RDD-SERIES DIRECT DR	IVE		0	0	4	3	3	0
	SX-SERIES EXPLOSION PROO	F MOTO	R	0	0	1	1	1	0
	VP LOW INERTIA SERVO M	OTOR		2	3	0	0	0	0
	<								>

OLUTIONS LIST	Vie	ewing 1 - 5 of 5 Sort by:	Choose Sort.		~						
			Choose Sort.		~	-					
Clear Filters		Note: Some solutions may ha	a Profile Match	Profile Match (%) 'our filter criteria.							
Solution Filters		> Filter Solutions by Pr	rc List Price	List Price							
Solution Filters (6)		Unable to calculate solutions	f Average Pow	er							
Solution Filters (0)	'	Drive	Bus Utilizatio	n		d Curve			Select		
Motor Filters		Kinetix 5700   2198-D020-ERS3	Winding Tem	mp.		u Curve					
Commonly Used (6)	>	Motor VPL Motor   VPL-B1306C-xxxxx	x Inertia Ratio		~	Average Current	Force Or Torque	Inertia Ratio	Peak Current	Thermal Capacity	
Torque/Force Ratings (6)	>	Gearbox		<b>76.</b> 1%	\$\$\$\$\$\$	9.43	Utilization 87.8%	62.17	0tilization 87.3%	84.5%	
Induction Motor (5)	>										
Physical Dimension (3)	>	Drive Kinetix 5700   2198-D032-ERS3		View To	orque Spee	d Curve			Sele	ct	
Options (14)	>	Motor VPL Motor   VPL-B1306C-xxxxxx	x	Profile Match	Relative Price	Average Current	Force Or Torque	Inertia Ratio	Peak Current	Thermal Capacity	
IP Ratings (5)		Caarbay		79 6%	*****	9 /3	Utilization	62 17	Utilization	79 4%	

8. Next, sort the solution list by **Bus Utilization** in the Sort by dropdown menu.

Clear Filters		Note: Some solutions may have access	ories added	to meet y	our filter	criteria.		•	
Solution Filters		> Filter Solutions by Product Far	nily					L	
Solution Filters (6)	>	Unable to calculate solutions for this axi Drive	S.						_
Motor Filters		Kinetix 5700   2198-D020-ERS3	View T	orque Spee	ed Curve			Sele	ect
Commonly Used (6)	>	Motor VPL Motor   VPL-B1306C-xxxxxxx	Profile Match	Relative Price	Average Current	Force Or Torque	Inertia Ratio	Peak Current	Thermal Capacity
Torque/Force Ratings (6)	>	Gearbox	7 <b>6</b> .1%	\$\$\$\$\$\$	9.43	87.8%	62.17	87.3%	84.5%
Induction Motor (5)	>								
Physical Dimension (3)	>	Urive Kinetix 5700   2198-D032-ERS3	View T	orque Spee	ed Curve			Sele	ect
Options (14)	>	Motor VPL Motor   VPL-B1308C-xxxxxxx	Profile Match	Relative Price	Average Current	Force Or Torque	Inertia Ratio	Peak Current	Thermal Capacity
IP Ratings (5)	>	Gearbox	79.6%	\$\$\$\$\$\$	9.43	Utilization 86.3%	62.17	Utilization 87.3%	79.4%
Certifications (3)	>								
Environment (3)	>	Drive Kinetix 5700   2198-D057-ERS3	View T	orque Spee	ed Curve			Sele	ect
Feedback (2)	>	Motor	Profile	Relative	Average	Force Or	Inertia	Peak	Thermal
Group (1)	>	Gearbox	74.3%	Price \$\$\$\$\$\$	9.43	Utilization 86.3%	62.17	Utilization 87.3%	Capacity 79.4%
Drive Filters									
Commonly Used (7)	>	Drive Kinetix 5700   2198-S086-ERS3	View T	orque Spee	ed Curve			Sele	ect
Voltage & Phase (4)	>	Motor	Profile	Relative	Average	Force Or	Inertia	Peak	Thermal
IP Ratings (5)	>	HPK-B1307C-x00000x   HPK-B1307C-x00000x	Match	Price	Current 24.78	Torque Utilization	Ratio 0.62	Current Utilization 51.4%	Capacity
Environment (3)	>	Genbox						2	
Options (4)	>	Drive	View T	orque Spee	ed Curve			Sele	ect
Certifications (19)	>	Motor							
Controller (4)	>	HPK-B1307C-xxxxxx   HPK-B1307C-xxxxxxx	Profile Match	Relative Price	Average Current	Force Or Torque Utilization	Inertia Ratio	Peak Current Utilization	Thermal Capacity
Eastures (35)	>	Gearbox	69.6%	\$\$\$\$\$\$	24.78	9.9%	0.62	51.4%	46.7%

9. Select the first solution option as shown below by clicking the **Select** button next to that combination.



10. Notice how your selection is added to your project while the project is then automatically saved.

11. Next, we will select the configuration for the motor and drive. Click on the **Select Configuration** for the VPL motor.



12. The new page will display the product line and opens at the VP Low Inertia Servo Motor Configuration Selection page. Select the first option with no DC brake and the single-turn absolute feedback type.



13. Click the Save Axis button to set the configuration.



14. Click the **OK** button in the dialog box that appears to return to the Axis page.



15. Next, we will select the configuration for the Kinetix 5700 drive. Scroll to the right in the Components section of the page to see the options for the selected Drive. Then, click the **Select Configuration** button for the Kinetix 5700 drive.



16. Select the Dual Axis Inverter feature of the Kinetix 5700 drive, then click the **Save Axis** button to set the configuration.



17. Click the **OK** button in the dialog box that appears to return to the Axis page.

Successfully saved item. Go to axis?		
	ок	
	CANCEL	

18. Click on the **Performance** tab to see the performance curves for the solution you have selected.



19. The Performance page for the axis allows you to analyze the Torque/Speed, Power/Speed, and Thermal Performance plots for the solution you have selected.



NOTE: As you can notice, Motion Analyzer performed a simulation and provided results in regards to your selected solution. Given this notification on the drive side, you may select to size up your drive to provide the power necessary for your application.

20. Click Size Up on the Drive solution section.

Summary	Drive Motor	
Selected So	lution (1 Available)	< >
Motor		
Size Down	VPL-B1306C-xxxxxx	Size Up <b>&gt;</b>
Thermal Capacity:	_	79.4%
Peak Speed:	•	10.3%
Peak Torque:		64.6%
Inertia Ratio	62.17 : 1	
Drive		
<size down<="" td=""><td>2198-D020-ERS3</td><td>Size Up≯</td></size>	2198-D020-ERS3	Size Up≯
Thermal Capacity:	_	84.5%
Average Current:		83.5%
Peak Current:		55.1%
Bus Utilization:	-	17.1%

### 21. Your solution should now look as follows





### 22. Select Apply on the new solution and then select the Duplicate option to duplicate your axis.

23. You will then be asked for a location for your duplicated axis. Select [Current Project]. Rename the new copy of the axis to Axis 2. Then select **Yes**, Duplicate this Axis.



24. Duplicating the axis will send you to the Component Detail page where you will see each created/copied axis. Click on the **Power Analysis** tab for the application.

★ \ Library \ Vertical Lift Application		
Vertical Lift Application 🖌	0 Shared Users Y 0 Comments Y	START EDITING
moves load	Automatically Saved	
		TREATE A SNAPSHOT
DOPLICATE DELETE EXPORTASX	ML	B RESTORE FROM SNAPSHOT
Summary Component Detail	Power Analysis Customer/Site Selected Products	
Vertical Lift Application Components		AXES (2)
		PROJECT ACTIONS
Axis: Axis 1		Create New Axis & Profile
Axis:	Dele	Create New Blank Axis
		Import Axis
Axis: Axis 2	Edit Dele	ete
Axis:		ote

25. The Power Analysis page includes information on power and bus utilization. Select **Auto Configure** option to see your DC bus Voltage Utilization.



Seconds 🔻	250	00:375	00:500	00:625	00:750	00:875	01:000	01:125	01::	C Timeline Adjustment:
DC BUS VOLTS										÷ +
0.000										

- 26. Repeat Step 25 once you select Axis 2 in your *Choose An Item To View section*. Your Selected Axis Detail should have the same calculation results as Axis 1.
- 27. Once done checking your utilization results, select the Share option to share the axes to a common bus.



#### **POWER ANALYSIS GRAPH**

Seconds 🔻	500	02:250	03:000	03:750	04:500	05:250	06:000	06:750	07:!	🖒 Timeline Adj	ustment:
DC BUS VOLTS										-	+
000.818											

28. Click on the Add to Group option and select the Share Control Power tab then Save.

[KINETIX 5700 SERVO DRIVE] SET DC BUS SHARING	Add Cluster
Axis 1 / [2198-D032-ERS3]	
Axis 2 / [2198-D032-ER\$3]	Add to Group
	Cancel Save

29. Your axes are now combined into a common bus and common control power. Motion Analyzer simulates these new calculations and provides updated results.

Shared Buses (0)	Standalone Axes (2)	SELECTED AXIS DETAIL	
M TO VIEW			
		Average Power Usage	C
	1	Average Motoring Power	C
		Average Regen Power	C
		DC Bus Voltage Utilization	
		DC Bus Rms Current Utilization	
		DC Bus Peak Current Utilization	
		lization	
	:		
		SET POWER SUPPLY, SHUNT,	AND
		Configures Axis power options based manual/automatic selections below. T selections.	on Axis his doe

30. You can now view accurate data from the **Selected Shared DC Bus Detail** section. Sharing your DC bus is reflected in the new calculations of your DC Bus Voltage Utilization.



31. Scroll down the Selected Shared DC Bus Detail to view the rest of your calculations

Power Supply	Auto	Manual
2198-P031		X
Continuous Converter Utilization		9%
Peak Power Utilization		11%
Shunt 1	Auto	Manual
Continuous Shunt Utilization		10%
Capacitor (1	Auto	Manual
		· · · · · · · · · · · · · · · · · · ·
32. You can also review your Power Analysis Graph by scrolling through the Application page.



## POWER ANALYSIS GRAPH

**NOTE:** For this application, the Shunt Utilization is within the acceptable range, so there is no need to add additional shunts or capacitor modules.

## Extra:

1. In your *Power Analysis Graph*, you can select to sync your axis by selecting Manual Entry from the *Select Analysis* dropdown.



POWER ANALYSIS GRAPH

2. Set Axis 2 to a 720 sec offset to Axis 1. Then select Update to view the recalculated values of your Selected Shared DC Bus Detail.



POWER ANALYSIS GRAPH

This completes the Motion Analyzer Lab.

Notes:

## www.rockwellautomation.com

## Power, Control and Information Solutions Headquarters

Publication XXXX-XX###X-EN-P — Month Year Supersedes Publication XXXX-XX###X-EN-P — Month Year

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